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First Results on the Experimental Validation of the SKA-low Prototypes Deployed in Australia Using an Airborne Test Source

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Abstract

As the Square Kilometre Array progresses toward the construction phase, the first prototypes of the low-frequency instrument have been deployed in Australia. To support such a crucial phase, a measurement campaign took place in the Murchison Radio-astronomy Observatory area in order to validate the electromagnetic models of the arrays by characterizing the embedded-element patterns and the array beams. A set of significant results is shown in this contribution.

1 Introduction

The future Square Kilometre Array (SKA) [0] radio telescope is approaching the final stage of its development. Within the bridging phase of the low-frequency instrument (SKA-low) [2], which will operate from 50 to 350 MHz, two stations have been built in the Murchison Radio-astronomy Observatory (MRO) area in Western Australia (see Figs. 1 and 2). Both the stations share a random array layout of 256 dual-polarized antennas mounted on a ground plane with a diameter of about 40 m. The Aperture Array Verification System 2.0 (AAVS2.0) station is composed of log-periodic SKALA4.1-AL antennas [3], whereas the Engineering Development Array 2 (EDA2) [4] station is composed of bow-tie antennas already used in the Murchison Widefield Array (MWA) [5].

The accuracy of the electromagnetic models is a critical aspect for such advanced instruments. The embedded element patterns (EEPs) can present significant distortions with respect to the expected behavior [6]. In June 2019, a measurement campaign was carried out at MRO with the main purpose of validating the electromagnetic models of both arrays through an experimental measurement of the EEPs and the digitally beam-formed array patterns exploiting a radio-frequency test source mounted on a small unmanned aircraft. The measurements directly involved research institutions from Italy, Australia and Malta. Before this campaign, the Italian team conducted several activities on low frequency aperture arrays, including the instrumental calibration [7-9] and near-field verification strategies [10, 11]. This contribution shows the relevant results of the MRO campaign.

2 Experimental Setup

When the MRO campaign was carried out, 48 antennas out of 256 were deployed in 3 clusters of 16 antennas for AAVS2.0, for this reason its name was AAVS1.5 [12]. EDA2 was fully deployed but only 48 antennas where connected to the receiver. The arrays shared nearly the same configuration. In particular, the layout of AAVS1.5 (illustration in Fig. 3) is slightly enlarged with respect to



Figure 1. Aerial view of the AAVS1.5 and EDA2 stations at the MRO site. Picture from <u>https://virtualtours-external.csiro.au/MRO/</u>



Figure 2. The AAVS1.5 SKALA4.1-AL antennas (left) and the EDA2 bow-tie dipoles (right).



EDA2 to accommodate the larger footprint of the elements. The resulting station diameter is 40 m for AAVS1.5 and 35 m for EDA2.

The measurements at MRO have been carried out by using the Unmanned Aerial Vehicle (UAV) system already adopted in [13], [14]. A small multicopter equipped with a Real Time Kinematic (RTK) differential GPS and a tunable radio-frequency generator operated as a flying test source.

The measurements have been performed at the frequencies of 50, 70, 110, 160, 230 and 320 MHz. They consisted in linear scans at a constant height of 120 m or 160 m to characterize the principal cuts of the radiation patterns with an angular coverage of $\pm 45^{\circ}$ from zenith [15]. Although at such flying height the test source was not in the far-field of the whole array (considering the three deployed clusters), the far-field condition was satisfied at the embedded-element level.

3 Results

Although a relatively small subset of antennas was deployed when the campaign took place, more than 10 GB of data have been collected in two days, corresponding to 14 flights, despite the weather conditions characterized by frequent wind gusts at 40 km/h.

In Fig. 4, the EEPs of two antennas (#0 and #2 of cluster #0) at two different frequencies are shown for the AAVS1.5 station. Antenna #0 is located at the edge of the cluster whereas #2 is closer to other adjacent antennas. Fig. 5 shows the results for the corresponding antennas in the EDA2 station. As previously mentioned, both the arrays share the same layout. We generally observe a good agreement between measurements (blue curves) and simulations (red curves). Similar agreement levels have been obtained for the other 46 elements, a detailed statistical analysis will be shown at the conference.

Figs. 6 and 7 show the normalized beam-formed pattern of cluster #0 (16 antennas) of AAVS1.5 and EDA2, respectively. As expected, the results are rather similar to each other, even though some elements present different behavior. The measured array pattern (blue) has been obtained by equalizing the complex EEPs at the zenith of the cluster. This corresponds to a near-field focusing. The simulations (red) are instead performed in far-field using the Method of Moments (MoM) of Galileo-EMT. The good agreement confirms the effectiveness of near-field focusing for array testing [16].

4 Conclusion

This first measurement campaign in Western Australia using a UAV-mounted test source has been conceived to support the deployment the SKA-low prototypes and verify the array models. Further activities will concern the whole 256-elements stations both in terms of the pattern characterization (also adopting near-field strategies) and the evaluation of the instrument performance (e.g. sensitivity).



Figure 3. Layout of AAVS1.5. Antennas #0 and #2 of cluster #0 highlighted.

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Figure 4. Normalized embedded-element patterns of antenna #0 (upper row) and #2 (lower row) of AAVS1.5 (north-south polarization, cluster #0) at 70 MHz (left column) and 320 MHz (right column). Blue: measurements, red: simulations.



Figure 6. Normalized beam-formed pattern of cluster #0 of AAVS1.5 at 320 MHz. Blue: measurements, red: simulations.

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Figure 5. Normalized embedded-element patterns of antenna #0 (upper row) and #2 (lower row) of EDA2 (north-south polarization, cluster #0) at 70 MHz (left column) and 320 MHz (right column). Blue: measurements, red: simulations.



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