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Telescopio Nazionale Galileo

LRS: Acquisition system (setting and test)

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1. Introduction

1.1.Scope

This document is intended to describe the migration between one CCD acquisition system to another. The original system, the LRS acquisition system, works from the year 2000 and is integrated in the TNG Instrument Control System (ICS), the new one will be based on the **A**stronomical **R**esearch **C**ameras (ARC) controller and a new acquisition software system that has to be integrated in the TNG ICS [RD02].

At the beginning of this document, we will compare the different methods used by the two CCD controller to manage the scan and reading. We will describe the existing CCD waveforms, written with the waveform editor (skytech controller), the waveforms programmed with the assembler code (ARC controller) and the theoretical waveforms provided by e2v.

Following we will describe the results of the electronic tests of the clock sequences and finally we will show the results of the first tests with the CCD detector.

1.2. Additional information

No additional information, at the moment.

1.3. Contact information

Feedback on this document is encouraged. Please email to cosentino@tng.iac.es

1.4. Reference documents

[RD01]CCD42-40 NIMO Back illuminated High Performances CCD Sensor Datasheet

[RD02] LRS: Implementation of ARC controller

[RD03] LRS - Software Requirements Specification

2. The e2v 4240 CCD

In this paragraph are introduced some information about the e2v CCD 4240, that has been used for the programming/generation of the waveform sequences. More information and the characteristic of the e2v 4240 CCD can be found in [RD01].

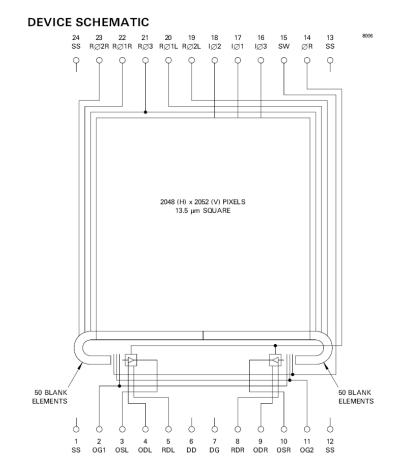


Figure 1 - Device Schematic

Table 1 - CCD Voltages

| | | | CLOCK LOW | | OCK HIGH | | MAXIMUM RATINGS |
|-----|------|----------------------------------|--------------|-----|--------------------------|-----|---------------------------------|
| PIN | REF | DESCRIPTION | Typical | Min | Typical | Max | with respect to V _{SS} |
| 1 | SS | Substrate | n/a | 0 | 9 | 10 | - |
| 2 | OG1 | Output gate 1 | n/a | 2 | 3 | 4 | ±20 V |
| 3 | OSL | Output transistor source (left) | n/a | | see note 9 | | -0.3 to +25 V |
| 4 | ODL | Output drain (left) | n/a | 27 | 29 | 31 | -0.3 to +25 V |
| 5 | RDL | Reset drain (left) | n/a | 15 | 17 | 19 | -0.3 to +25 V |
| 6 | DD | Dump drain | n/a | 22 | 24 | 26 | -0.3 to +25 V |
| 7 | DG | Dump gate (see note 10) | 0 | - | 12 | 15 | ±20 V |
| 8 | RDR | Reset drain (right) | n/a | 15 | 17 | 19 | -0.3 to +25 V |
| 9 | ODR | Output drain (right) | n/a | 27 | 29 | 31 | -0.3 to +25 V |
| 10 | OSR | Output transistor source (right) | n/a | | see note 9 | | -0.3 to +25 V |
| 11 | OG2 | Output gate 2 (see note 11) | 4 | 16 | 20 | 24 | ±20 V |
| 12 | SS | Substrate | n/a | 0 | 9 | 10 | - |
| 13 | SS | Substrate | n/a | 0 | 9 | 10 | - |
| 14 | ØR | Reset gate | 0 | 8 | 12 | 15 | ±20 V |
| 15 | SW | Summing well | | (| Clock as R \varnothing | í3 | ±20 V |
| 16 | IØ3 | Image area clock, phase 3 | 0 | 8 | 10 | 15 | ±20 V |
| 17 | IØ1 | Image area clock, phase 1 | 0 | 8 | 10 | 15 | ±20 V |
| 18 | IØ2 | Image area clock, phase 2 | 0 | 8 | 10 | 15 | ±20 V |
| 19 | RØ2L | Register clock phase 2 (left) | 1 | 8 | 11 | 15 | ±20 V |
| 20 | RØ1L | Register clock phase 1 (left) | 1 | 8 | 11 | 15 | ±20 V |
| 21 | RØ3 | Register clock phase 3 | 1 | 8 | 11 | 15 | ±20 V |
| 22 | RØ1R | Register clock phase 1 (right) | 1 | 8 | 11 | 15 | ±20 V |
| 23 | RØ2R | Register clock phase 2 (right) | 1 | 8 | 11 | 15 | ±20 V |
| 24 | SS | Substrate | n/a | 0 | 9 | 10 | - |

CONNECTIONS, TYPICAL VOLTAGES AND ABSOLUTE MAXIMUM RATINGS

If all voltages are set to the typical values, operation at or close to specification should be obtained. Some adjustment within the range specified may be required to optimize performance. Refer to the specific device test data if possible.

Maximum voltages between pairs of pins:

pin 3 (OSL) to pin 4 (ODL) +15 V

pin 9 (ODR) to pin 10 (OSR) +15 V

Maximum output transistor current. . 10 mA

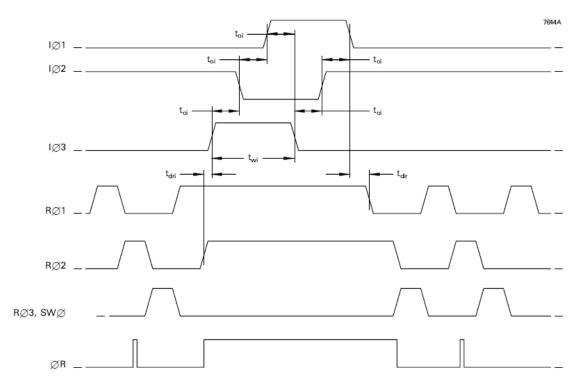
NOTES

9. Not critical; OS = 3 to 5 V below OD typically. Connect to ground using a 3 to 5 mA current source or appropriate load resistor (typically 5 to 10 kO).

10. This gate is normally low. It should be pulsed high for charge dump.

11. OG2 = OG1 + 1 V for operation of the output in high responsivity, low noise mode. For operation at low responsivity, high signal, OG2 should be set high.

12. With the R1 connections shown, the device will operate through both outputs simultaneously. In order to operate from the left output only, R11(R) and R12(R) should be reversed.



DETAIL OF LINE TRANSFER (Not to scale)



DETAIL OF VERTICAL LINE TRANSFER (Single line dump)

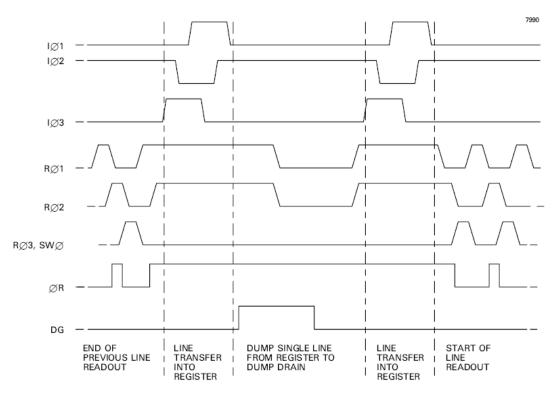
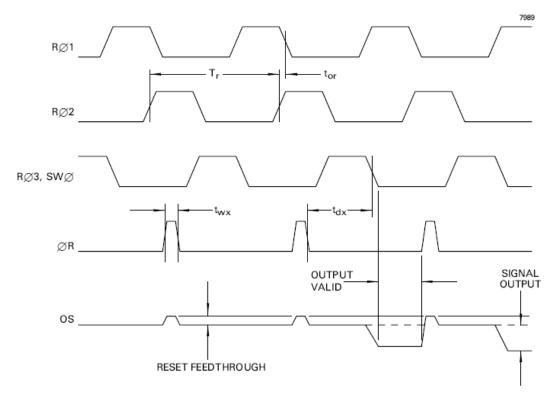


Figure 3 - Vertical Line Transfer



DETAIL OF OUTPUT CLOCKING (Operation through both outputs)

Figure 4 - Output Clocking (both output)

Table 2 - Clocking Timing

CLOCK TIMING REQUIREMENTS

| Symbol | Description | Min | Typical | Max | |
|-----------------------------------|---|-----------------------|--------------------|-------------------|----|
| Ti | Image clock period | 10 | 20 | see note 13 | μs |
| t _{wi} | Image clock pulse width | 5 | 10 | see note 13 | μs |
| t _{ri} | Image clock pulse rise time (10 to 90%) | 1 | 2 | 0.2T _i | μs |
| t _{fi} | Image clock pulse fall time (10 to 90%) | t _{ri} | t _{ri} | 0.2T _i | μs |
| t _{oi} | Image clock pulse overlap | $(t_{ri} + t_{fi})/2$ | 2 | 0.2T _i | μs |
| t _{dir} | Delay time, IØ stop to RØ start | 3 | 5 | see note 13 | μs |
| t _{dri} | Delay time, RØ stop to IØ start | 1 | 2 | see note 13 | μs |
| Tr | Output register clock cycle period | 300 | see note 14 | see note 13 | ns |
| t _{rr} | Clock pulse rise time (10 to 90%) | 50 | 0.1T _r | 0.3T _r | ns |
| t _{fr} | Clock pulse fall time (10 to 90%) | t _{rr} | 0.1T _r | 0.3T _r | ns |
| t _{or} | Clock pulse overlap | 20 | 0.5t _{rr} | 0.1T _r | ns |
| t _{wx} | Reset pulse width | 30 | 0.1T _r | 0.3T _r | ns |
| t _{rx} , t _{fx} | Reset pulse rise and fall times | 20 | 0.5trr | 0.1Tr | ns |
| t _{dx} | Delay time, ØR low to RØ3 low | 30 | 0.5Tr | 0.8T _r | ns |

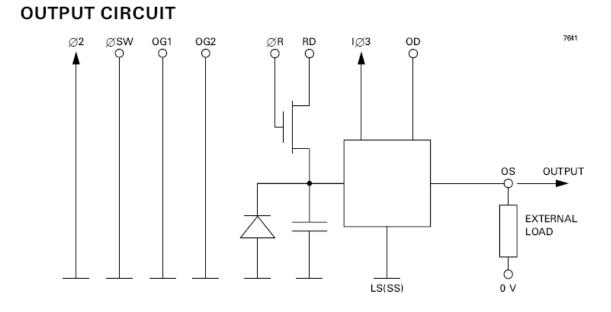


Figure 5 - Output Circuit

3. The Programmed Waveforms

The LRS CCD was used at TNG for a long time with the Skytech controller, and the waveforms was optimized to maximize the detector performances. The new ARC controller is provided with a template code, in assemble language, that has to be adapted to the CCD in use.

In this chapter are shown the different implementation of the waveform for both the acquisition systems.

3.1 The Waveform of the Skytech controller (WEditor)

The waveform shown in this paragraph was be used in the implementation of skytech CCD controller for LRS and was be programmed by using the Waveform Editor Program.

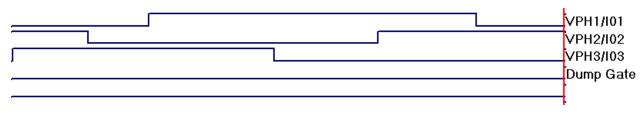


Figure 6 - Vertical phases (WE)

TNG-TS-LRS-0003

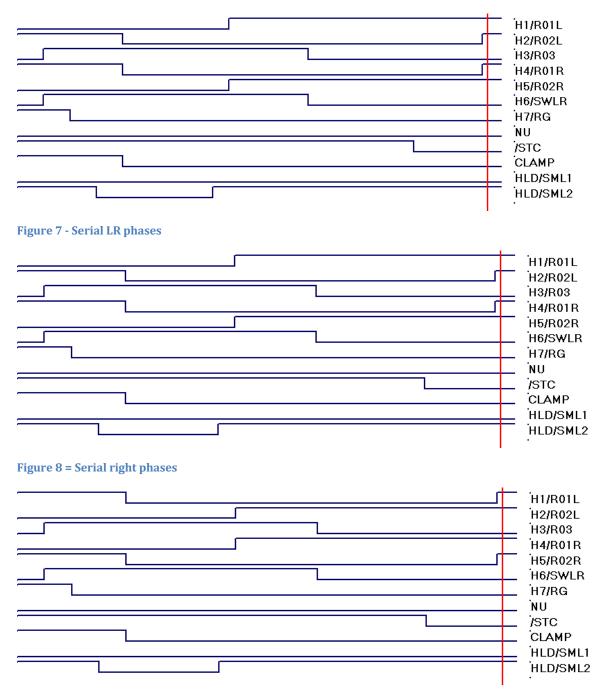


Figure 9 - Serial Right phases

3.2 The Waveform of the ARC controller (Assembler)

The waveforms for the ARC controller are generated by an assembler code and uses the Motorola 56000 DSP. An example of this code implementation of the sequences for the readout of the CCD in LR mode (readout from the two output of the CCD) is shown in the following figures.

9

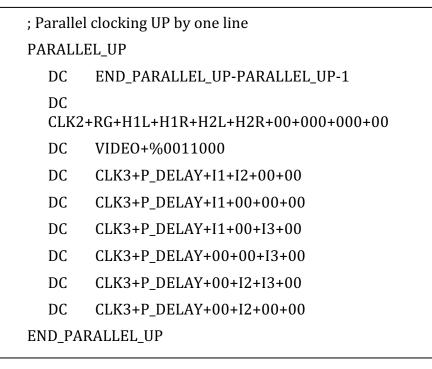


Figure 10 - Parallel clocking

| SERIAL_READ_SPLIT_MED | | | |
|-----------------------|---|---------------------|--|
| DC | END_SERIAL_READ_SPLIT_MED-SERIAL_READ_SPLIT | _MED-1 | |
| DC | CLK2+\$030000+RG+000+H2L+000+H2R+00+CLP | ; Reset output node | |
| DC | CLK2+\$000000+00+000+H2L+000+H2R+00+CLP | | |
| DC | VIDEO+\$010000+%1110100 | ; Reset integrator | |
| SXMIT_S | PLIT_MED | | |
| DC | \$00F000 | ; SXMIT | |
| DC | VIDEO+\$000000+%0010111 | ; Stop reset | |
| DC | VIDEO+\$040000+%0000111 | ; Integrate | |
| DC | CLK2+\$060000+00+000+H2L+000+H2R+H3+SW+CL | P | |
| DC | CLK2+\$0C0000+00+000+000+000+000+H3+SW | | |
| DC | CLK2+\$010000+00+H1L+000+H1R+000+H3+SW | ; Dump the charge | |
| DC | VIDEO+\$000000+%0010111 | ; Stop Integrate | |
| DC | VIDEO+\$000000+%0011011 | ; Change polarity | |
| DC | VIDEO+\$040000+%0001011 | ; Integrate | |
| DC | CLK2+\$060000+00+H1L+000+H1R+000+00+00 | | |
| DC | CLK2+\$060000+00+H1L+000+H1R+000+00+00 | | |
| DC | CLK2+\$070000+00+H1L+H2L+H1R+H2R+00+00 | | |
| DC | VIDEO+\$000000+%0011011 | ; Stop Integrate | |
| END_SEF | RIAL_READ_SPLIT_MED | | |

Figure 11 - Serial readout clocking (LR-Medium speed)

More readout more are implemented in the assembler code (Table 3) [RD03].

Table 3 - Readout modes implemented in the assembler code

| Section Name | Mode | Speed | Microsec/pixel |
|------------------------|-------|-------|----------------|
| SERIAL_READ_LEFT_SLOW | LEFT | SLOW | 10 |
| SERIAL_READ_LEFT_MED | LEFT | MED | 2.5 |
| SERIAL_READ_LEFT_FAST | LEFT | FAST | 1 |
| SERIAL_READ_RIGHT_SLOW | RIGHT | SLOW | 10 |
| SERIAL_READ_RIGHT_MED | RIGHT | MED | 2.5 |
| SERIAL_READ_RIGHT_FAST | RIGHT | FAST | 1 |
| SERIAL_READ_SPLIT_SLOW | SPLIT | SLOW | 10 |
| SERIAL_READ_SPLIT_MED | SPLIT | MED | 2.5 |
| SERIAL_READ_SPLIT_FAST | SPLIT | FAST | 1 |

4. Test of the Waveform with the oscilloscope

To optimize the noise level of the clocks and minimize the crosstalk, the approach was the measurement of the signals in different point of the electronic chain and with different implementation (controller, clock board, cables). In the following paragraph will be described the configurations used and the results obtained.

4.1.Skytech controller with the clock board

In this test the configuration is:

- CCD controller Skytech
- Original LRS TNG clock cables
- Clock board

To simplify the analysis of the results we considered the readout mode that read the CCD from both output.

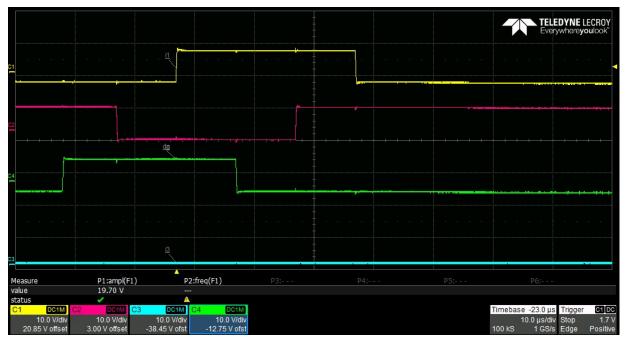


Figure 12 - Vertical waveforms

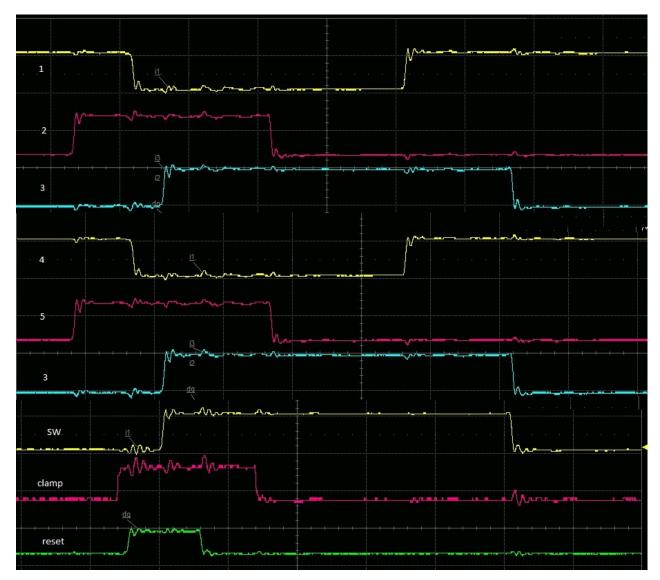


Figure 13 - Serial LR waveforms

4.2. ARC controller with the test board

In this test the configuration used is:

- CCD controller ARC
- Test board



Figure 14 - ARC controller and Test Board

In this test we used the "E2VLRS.waveforms" assembler code. This version of DSP assembler code is described in [RD03].

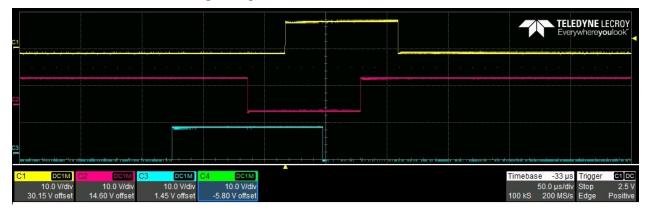


Figure 15 - Vertical waveforms

The serial RL waveforms have been analysed with different readout mode, to verify the degrading of the waveforms, depending on the readout speed. In the Fast-Mode test (Figure 16) a 'simulated' integration signal was added to have an idea of the processing operations.

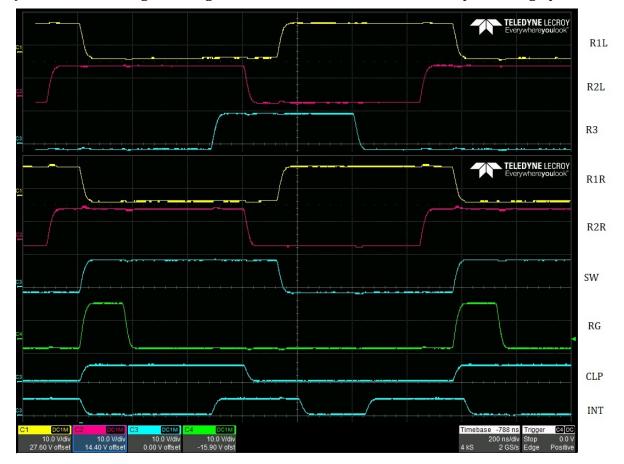
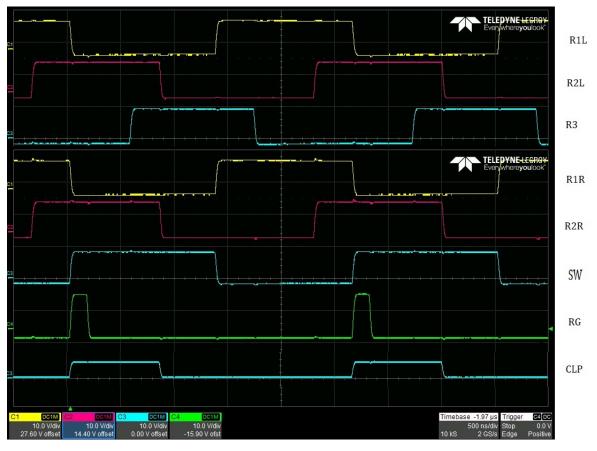
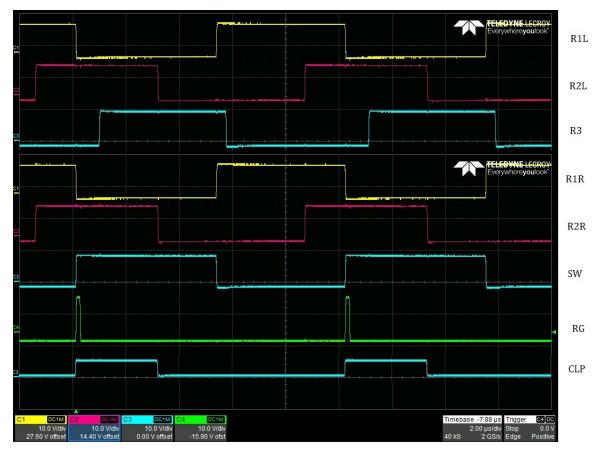


Figure 16 - Serial LR-FAST waveforms









The waveforms generated by the ARC controller are not degraded when the readout speed increases, the shapes of the clock signals don't show significant differences at 1, 2.5 or 10 μ sec/pixel readout speed.

4.3.ARC controller on the CCD board

4.3.1. Signal Measurement

These tests have been done with the real configuration for the CCD readout and taking the measure directly in the CCD socket:

- CCD controller ARC
- New custom clock cables
- New custom Video-Bias cable
- CCD Board (without CCD)

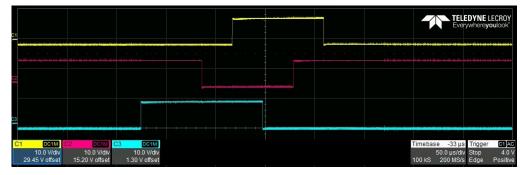


Figure 19 - Vertical Waveform

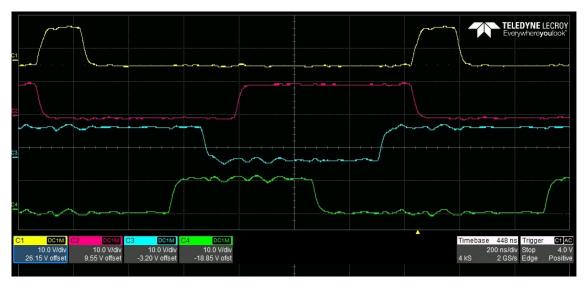


Figure 20 - Serial LR-FAST waveforms

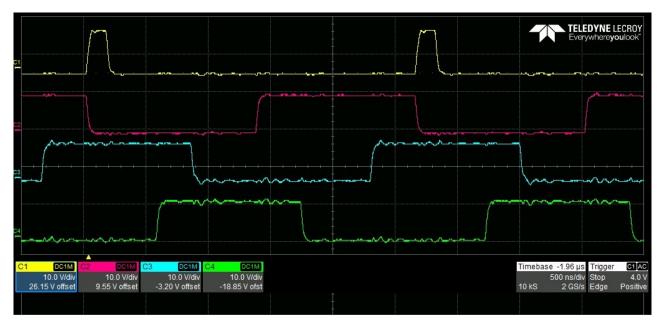


Figure 21 - Serial LR-MED waveforms

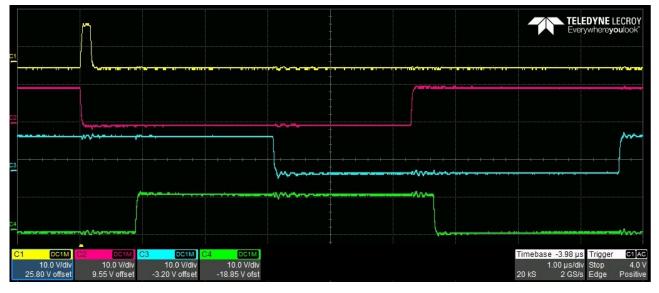


Figure 22 - Serial LR-SLOW waveforms

The clock signals generated by the ARC controller, measured in the CCD socket, are compliant with the specifications and the quality of them are compliant with the signals requested by the CCD.

4.4. CCD acquisition

After the test at CCD socket level, we are ready to test the e2v 42-40 CCD with the new acquisition system based on the ARC controller.

The following tests will be:

- The readout of the engineering CCD, mounted in a proto box
- The test of the scientific CCD at room temperature, mounted in the LRS dewar
- the test and characterization of the cooled scientific CCD, mounted in the LRS dewar

4.4.1. Engineering CCD at room temperature

These tests were done with an engineering CCD, mounted in a proto box, at room temperature. In this condition is possible verify if the acquisition system works as expected, because the CCD image has to show the overscan and the dark signal. We have adjusted the video offsets to obtain the wanted value of overscan pixels (considered as bias) and we acquired three images, one for each readout speed.

The acquired images show that the dark signal increases with a gradient trend that depends by readout time of the CCD image (with the SLOW readout mode the dark current reach the saturation of the image in the upper part of the CCD).

Configuration:

- ARC controller with video-bias and Clock cables
- Preamplifier and clocks boards
- Testing bench (proto box) with the ccd detector

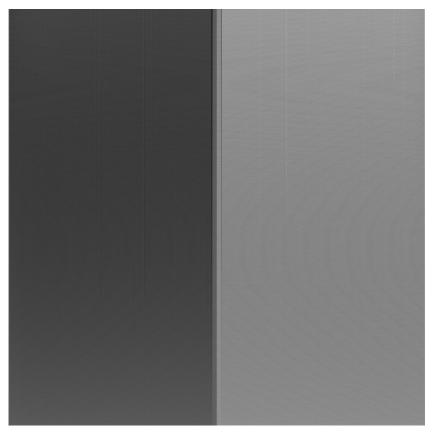


Figure 23 - CCD image at room temperature Readmode = LR-FAST

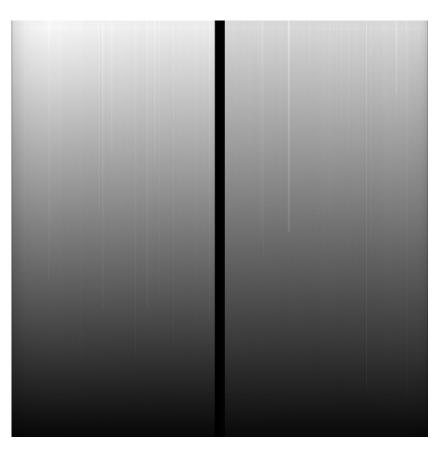


Figure 24 - CCD image at room temperature Readmode = LR-MED

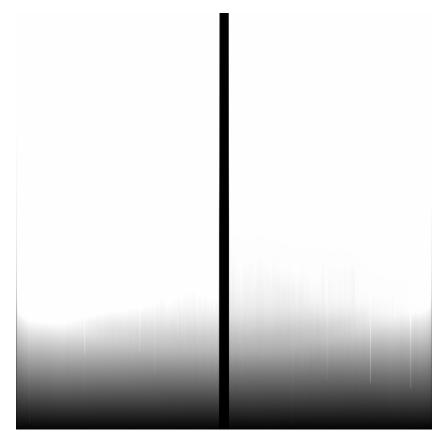


Figure 25 - CCD image at room temperature Read mode = LR-SLOW (saturated on the top of the image)

The results of the tests of the engineering CCD at room temperature shows that the acquisition system is working as expected.

The overscan of the two outputs are visible in the centre of the images, the cosmetic characteristics of the CCD is clearly visible and the gradient of the signal in the CCD area is according with the readout speed (more gradient at the increasing of the readout time).

The new acquisition system, based on the ARC controller passed the laboratory test and can be tested with the scientific CCD.

4.4.2. Scientific CCD at room temperature

The same test of the paragraph 4.4.1 was repeated with the e2v 42-40 scientific CCD, mounted in the LRS Dewar (Figure 26). The results were comparable with the test of the engineering CCD and demonstrated that the new CCD acquisition system can be used at the telescope as upgrade of the current one.

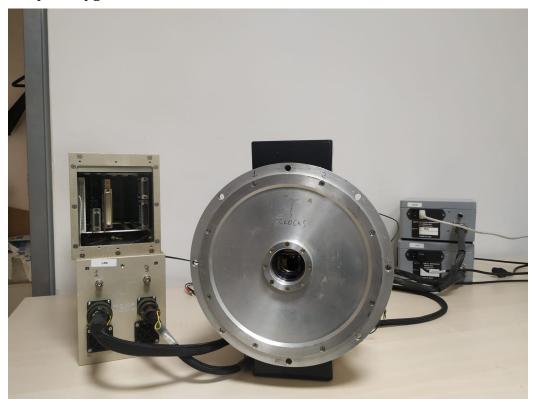


Figure 26 - LRS Dewar and ARC controller

4.4.3. Scientific CCD at cryogenic temperature

These tests are in stand-by and will be done as soon as the LRS detector will be available for the laboratory tests.

1. Appendix A – Document identification code

ORG-TYP-INS-NCOD

ORG = Originator field (i.e. TNG) TYP = Document Type (see Table 4) PRJ = project element (see Table 5) NCOD= numeric code (i.e. 0001)

Example: TNG-MAN-HAN-0001

Table 4 - Document type code

| AD | Assumption Document |
|-----|--|
| AN | AN Analysis |
| COS | Cost Documents (Estimate/CaC/CtC, etc) |
| DD | Design Description |
| DP | Data Package |
| DRD | Document Requirements Description/Definition |
| DRL | Document Requirements List |
| DW | Drawing/Diagram |
| EID | Experiment Interface Document |
| FI | File (Software/Configuration/Network) |
| ICD | Interface Control Document |
| IRD | Interface Requirement Document |
| ITT | Invitation to Tender |
| MAN | Manual/User Guide/Handbook |
| MEM | Memo |
| MOM | Minutes of Meeting |
| MOU | Agreement/Memorandum of Understanding |
| MX | Matrix/Compliance |
| NCR | Non-Conformance Report |
| NOT | Note |
| OPS | Operations Document |
| PLN | Plan |
| РО | Proposal |
| PRE | Progress Report/Status Report |
| RFQ | Request for Quotation |
| SOW | Statement of Work |
| TOR | Terms of Reference |
| TN | Technical Note |
| ТР | Test Procedure/Test Plan |
| TR | Test Report/Test Result |
| | |

| TS | Test Specification |
|-----|-------------------------------|
| VC | Verification Control Document |
| WBS | Work Breakdown Structure |
| WP | Working Paper |
| WPD | Work Package Description |

2. Appendix C – Project Element Code

Table 5 – Project element code

| BTM | Batman |
|-----|-------------------------------------|
| CCD | CCD detector/electronic/software |
| HAN | HARPSN |
| TRK | Tracking |
| LRS | Low Resolution Spectrograph for TNG |
| SRG | SARG |
| | |
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