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ABSOLUTE PROPER MOTIONS OUTSIDE THE PLANE (APOP)—A STEP TOWARD THE GSC2.4

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ABSTRACT

We present a new catalog of absolute proper motions and updated positions derived from the same Space Telescope Science Institute digitized Schmidt survey plates utilized for the construction of Guide Star Catalog II. As special attention was devoted to the absolutization process and the removal of position, magnitude, and color dependent systematic errors through the use of both stars and galaxies, this release is solely based on plate data outside the galactic plane, i.e., $|b| \geq 27^\circ$. The resulting global zero point error is less than 0.6 mas yr^{-1} , and the precision is better than 4.0 mas yr^{-1} for objects brighter than $R_F = 18.5$, rising to 9.0 mas yr^{-1} for objects with magnitudes in the range $18.5 < R_F < 20.0$. The catalog covers 22,525 square degrees and lists 100,774,153 objects to the limiting magnitude of $R_F \sim 20.8$. Alignment with the International Celestial Reference System was made using 1288 objects common to the second realization of the International Celestial Reference Frame (ICRF2) at radio wavelengths. As a result, the coordinate axes realized by our astrometric data are believed to be aligned with the extragalactic radio frame to within $\pm 0.2 \text{ mas}$ at the reference epoch J2000.0. This makes our compilation one of the deepest and densest ICRF-registered astrometric catalogs outside the galactic plane. Although the Gaia mission is poised to set the new standard in catalog astronomy and will in many ways supersede this catalog, the methods and procedures reported here will prove useful to remove astrometric magnitude- and color-dependent systematic errors from the next generation of ground-based surveys reaching significantly deeper than the Gaia catalog.

Key words: astrometry – astronomical databases: miscellaneous – catalogs – proper motions – reference systems

1. INTRODUCTION

The Second Generation Guide Star Catalog, or GSC-II, is an all-sky catalog of objects built from the Digitized Sky Surveys that the Space Telescope Science Institute (STScI) created from the Palomar and UK Schmidt survey plates (GSC2.3, Lasker et al. 2008). The GSC-II was primarily created to continue providing guide star information⁶ and observation planning support, including protection from nearby bright objects to the new generation ultra-sensitive cameras installed on the *Hubble Space Telescope* (*HST*) since the first GSC. Thanks to its relatively faint magnitude limit and multi-band photometry, GSC-II is also employed at some of the largest ground-based facilities such as GEMINI, the Very Large Telescope, and LAMOST. In the most recent version (GSC2.3.4 in *HST* operations), it was found that the derived proper motions, although compliant with the Hubble operations, suffered from significant systematic errors, especially in the southern hemisphere, and for this reason they were not included in the version released to the astronomical community. This limited the scientific and also technical (e.g., accurate operation of multi-fiber spectrographs) usefulness of the public GSC2.3; various experiments were then initiated to investigate the sources of such systematic errors and to explore alternative methods for improving the proper motion accuracy (Spagna et al. 2004; Tang et al. 2008). Astrophysically, large samples of accurate absolute proper motions to faint magnitudes are

fundamental observables in Milky Way studies to gain, e.g., further insight into the recently discovered evidence of unexpected chemo-kinematical features (Spagna et al. 2010). These new findings bear the potential to shed new light on the origin and evolution of our Galaxy (Curir et al. 2012, 2014), and ultimately on its role in cosmology (Lattanzi 2012).

In this paper we concentrate on the recalibration of the GSC-II proper motions; however, we also discuss the catalog release (which includes a recalibration of the positions); the catalog, in the form presented here, will be made available at the Strasbourg astronomical Data Center (CDS) with the publication of this article.

Assuming we can consider the proper motions of galaxies to be zero, there are two ways to exploit this in the determination of absolute proper motions.

1. One is the *direct* way; here, all the observations obtained at different epochs are directly transformed into one system using galaxies as reference objects; therefore, absolute proper motions are a natural derivation within this approach.
2. The other possibility is to bring all the observations into a common system using stars (instead of galaxies) as reference objects from which to calculate relative proper motions of all of the measured objects. Then, render those proper motions absolute by subtracting the pseudo proper motions of the galaxies.

The GSC-II object classification is based on star/non-star criteria rather than star/galaxy. This was done for operational

⁶ In this respect, GSC-II includes the first generation GSC, or GSC-I (Lasker et al. 1990).

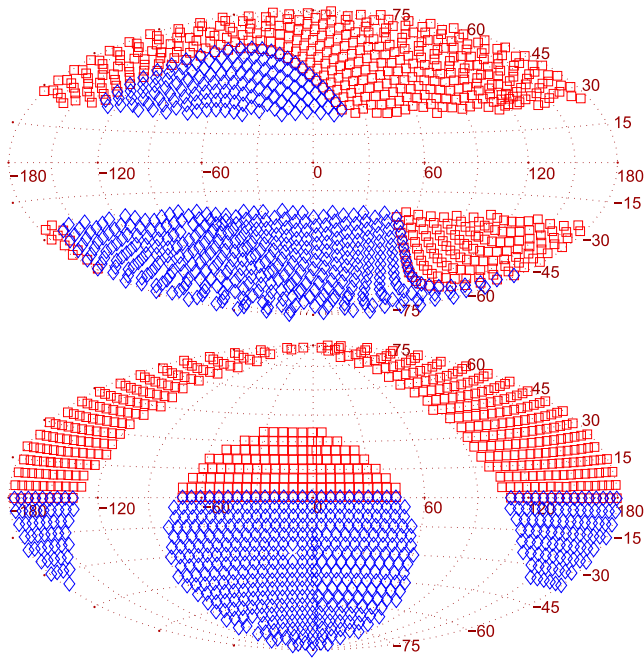


Figure 1. Sky distribution of the Schmidt plates used in the APOP catalog. There are 4239 plates used in the reductions. The total area covered by this catalog is $22,525 \text{ deg}^2$. The top figure represents the celestial sphere in Galactic coordinates and the bottom is its analog in Equatorial coordinates. The blue diamonds represent plates with $\delta < 0^\circ$ and the red squares those with $\delta \geq 0^\circ$.

reasons in order to prioritize the reliability of the star classification at the cost of a less accurate, more generic, non-star classification. Therefore, non-stars will be a mix of blended objects, faint stars, and galaxies, providing a heterogeneous reference system. This mixing is not easy to disentangle, leading to imprecise astrometric transformations; furthermore, the individual accuracy of the measured positions for the non-stars is generally worse than that for stars. Therefore, after a number of dedicated evaluation tests, we decided to adopt the second procedure.

Due to increasing interstellar extinction as we approach the galactic plane, the number of observable (genuine) galaxies drops to zero. In the end, our reductions only addressed the parts of the celestial sphere with galactic latitudes $|b| \geq 27^\circ$; see Figure 1. This is only an operational definition of off-the-galactic-plane regions, and clearly depends on the lack of non-stars for our reductions below that latitude.

The next section describes the plate data used to derive the proper motions in our catalog, which we decided to call “Absolute Proper motions Outside the Plane,” or APOP, for brevity.

In the 3rd section we present the calibration pipeline and the details of the detection and removal of systematic errors that are dependent on plate position, magnitude, and color (hereafter PdE, MdE, and CdE, respectively).

In Section 4, the anticipated precision is estimated theoretically, and both internal and external precisions are assessed. This section also describes the APOP available to the community through the CDS center in Strasbourg. Finally, the last section presents some conclusions and briefly discusses future plans.

2. PLATE DATA

The observational data come from the STScI Catalog of Objects and Measured Parameters from All-Sky Surveys (COMPASS) archive of the GSC-II project (see Lasker et al. 1998). This object-oriented database is the repository of the original (raw) measurements (astrometric and photometric) of all of the objects detected on any of the 9000+ survey plates digitized at STScI; it also contains the entire set of parameters resulting from all of the plate-based calibrations (object detection and inventorying, astrometry, photometry, and image classification). Below we summarize the properties of the data in the COMPASS repository that are useful for better understanding the next sections (precise references to the relevant parts of the 2008 work of Lasker et al., or other published papers, are provided whenever appropriate):

1. Sky coverage and epochs. The different photographic plate collections inventoried in COMPASS cover all directions of the celestial sphere at least a few times over the timespan they comprise. The Northern declinations were observed with time differences that span from a minimum of ~ 25 years to as much as 50 years. For the Southern sky the situation is distinctively less homogeneous: for the declinations in common with those reached by the Palomar Observatory Schmidt telescope first epoch campaigns ($\delta \geq -30^\circ$), epoch differences can extend to 50 years; however, intervals as short as a few years can occur further South. The details of the decl. ranges reached by each individual Schmidt plate survey and the corresponding epoch intervals are in Table 1 of Lasker et al. (2008);
2. Photometric bands. Table 1 of Lasker et al. (2008), along with their Figure 1, provides information on the photometric data in COMPASS. In particular, the relation of the photographic passbands R_F , B_J , I_N with the Johnson–Kron–Cousins $B V R I_c$ photometric system is clearly illustrated, with B_J significantly extending into the wavelength range of the photometric V . Although only B_J and R_F magnitudes are explicitly utilized in this article, all of the GSC-II based photographic magnitudes are listed with the APOP entries (see Table 1 in Section 4.4);
3. Cross-identification of the same objects detected on different plates was made using a matching radius of 4 arcsec;
4. The digitized resolution of most plates is $15 \mu\text{m}/\text{pixel}$ (1 arcsec/pixel), while some plates were scanned at $25 \mu\text{m}/\text{pixel}$ (1.7 arcsec/pixel; details in Table 1 of Lasker et al. 2008);
5. Errors. The average error of the measured plate coordinates is about 0.12–0.13 pixel at intermediate magnitudes, i.e., brighter than 18.5 (Spagna et al. 1996); also, the average photometric error is within 0.13–0.22 mag ($16 \text{ mag} < R_F < 20 \text{ mag}$);
6. GSC2.3 Classification. The reliability of star classification remains above 90% to $R_F = 19.5$, and better than 95% to $R_F = 18.5$, while that of non-stars classified as galaxies is significantly less (Right panel of Figure 29 in Lasker et al. 2008), with numbers always below 85% and to a low of 70% at the faint limit.

The success of the procedures we have adopted for the APOP construction relies heavily on the accuracy of the classification of both stars and galaxies. Besides, as already

stated in the previous section and quantified in the last of the GSC2.3 properties above, classification is limited to star/non-star, with no galaxy class, which complicates the calculation of absolute proper motions. Therefore, before going into the details of the astrometric calibration algorithms discussed in Section 3, these are two facts that are important to clarify here. First, the error of the measured coordinates and the property of accurately classifying stars to 95% confidence down to $R_F = 18.5$ completely justifies the $16 < R_F < 18.5$ mag range as the interval of choice for the reference (anonymous) stars utilized in the initial plate-to-plate astrometric reductions. Then, the precise knowledge that the classification of non-stars as galaxies is significantly less reliable was the motivation for developing the new procedure to iteratively refine the selection of genuine galaxies from the non-star objects for improved final astrometric calibrations and proper motion absolutization.

3. CATALOG CONSTRUCTION

There are three critical factors affecting errors of absolute proper motions: (a) the epoch range spanned by the survey plates employed, (b) the quality (e.g., intrinsic noise) of the emulsions of that same photographic material along with that of the measuring machines utilized for the digitization process, and (c) the modeling of the transformation of plates of different epochs to a common reference frame. The third element is really the only one we can work on to improve the calibrations and hopefully derive better proper motions.

It is well known that because of the combined influence of the atmosphere (differential refraction, dispersion, extinction etc.), telescope (guiding errors, distortion of field of view, etc.), photographic plates (uneven response to bending stress, size and distribution of emulsion, low quantum efficiency etc.), and plate scanner (digitizing errors), individual plate coordinates of the detected objects, as well as their magnitudes and colors, can have varied systematic errors that are dependent on the position, magnitude and color of the same objects, and these systematics can be different for the different survey plates (see for example Taff et al. 1990; Morrison et al. 1998; Evans & Irwin 1995; Kuimov et al. 2000).

As proper motions are derived from positions at different epochs, it is likely that they will suffer from similar systematic errors. On the other hand, actual (physical) proper motions are expected to exhibit correlations with sky direction, magnitude and color due to the motions of the different stellar populations within the Milky Way. Therefore, one aspect that must be carefully considered when attempting the elimination of the systematic errors mentioned above is not to bias the proper motions with unphysical sources.

Below, we describe both the reduction procedures and assumptions adopted.

3.1. Principles of Calibration

Following the work by van Altena et al. (1990), Spagna et al. (1996), and, more recently, by Mahmud & Anderson (2008), Kallivayalil et al. (2013) and Pryor et al. (2014), we work under the hypothesis that the absolute proper motions of galaxies are always zero, i.e., they are not dependent on their plate position, magnitude, or color. To this we add a second hypothesis: objects (stars and galaxies) physically close on a photographic plate and with similar magnitudes/colors have similar systematic errors.

Based on these assumptions, and considering the available plate data, the adopted procedure is to choose a good quality plate as the reference plate and to use the objects classified as stars with good image quality to transform the relevant program plates to the reference plate system. Here good image quality means objects in the middle of the unsaturated magnitude range (i.e., $16.0 < R_F < 18.5$) where the centering errors are minimized, i.e. ~ 0.13 arcsec, see Section 2.

The major plate-based calibration steps are:

1. Remove the PdE with a moving-mean filter⁷ using stellar objects with good image quality;
2. Select galaxies from non-stars via their pseudo (common) motion relative to the reference stars; and
3. Calibrate the MdE, CdE and the residual PdE of all objects with reference to the galaxies.

Finally, absolute proper motions are calculated from all of the detections at the different plate epochs.

The relevant equations are described below.

For each object, the difference of positions between the reference (plate 1) and one of the corresponding program plates (plate 2) is modeled as

$$\Delta x_s = x_1 - x_2 = \mu_x \Delta t + D(x_2, y_2) + E(m_2, c_2, x_2, y_2) \quad (1)$$

$$\Delta x_g = D(x_2, y_2) + E(m_2, c_2, x_2, y_2), \quad (2)$$

where Δx_s , Δx_g represent the individual positional difference of stars and galaxies, respectively, and μ_x is a star's absolute proper motion in the reference plate coordinate system; also, Δt is the epoch interval between the reference and program plates, D is the PdE, and E is the combined MdE and CdE. Similar equations hold for the y coordinate.

The absolute proper motion μ_x of each star can be separated into the average proper motions $\bar{\mu}_x$ for all reference stars on the plate and a remaining individual proper motion, relative to the reference stars, $d\mu_x$, i.e.,

$$\mu_x = \bar{\mu}_x + d\mu_x. \quad (3)$$

Removing the systematic error D , besides removing the average MdE and CdE of the reference stars, also removes their average proper motions $\bar{\mu}_x$, while the galaxies will attain a "pseudo" proper motion $-\bar{\mu}_x$.

After this step, the position differences $\Delta x'_s$, $\Delta x'_g$ of stars and galaxies between the reference and program plates can be expressed as:

$$\Delta x'_s = x_1 - x'_2 = \Delta x_s - (D + \bar{\mu}_x \Delta t) = d\mu_x \Delta t + E \quad (4)$$

$$\Delta x'_g = \Delta x_g - (D + \bar{\mu}_x \Delta t) = -\bar{\mu}_x \Delta t + E. \quad (5)$$

Equation (5) has a special role in our reduction procedure; we iterate exactly on this equation to reject non-stars that are not genuine galaxies. In practice, assuming that all real galaxies will show the common pseudo proper motion $-\bar{\mu}_x$ discussed before, we flag as outliers, i.e., probable blended objects, those that do not.⁸ In the end, the selected true galaxies constrain the average proper motions, and MdE and CdE terms. After this

⁷ This moving filter, or moving sub-plate method as it is called in this article, is described in Section 3.3.

⁸ See Section 3.3 for details on thresholds set for outlier rejection.

stage, the updated position differences $\Delta x''_s, \Delta x''_g$ can be expressed as:

$$\begin{aligned}\Delta x''_s &= x_1 - x''_2 = \Delta'x_s - \Delta'x_g \\ &= d\mu_x \Delta t + E - (-\bar{\mu}_x \Delta t + E) \\ &= (d\mu_x + \bar{\mu}_x) \Delta t \\ &= \mu_x \Delta t \\ \Delta x''_g &= \Delta'x_g - \Delta'x_g = 0.\end{aligned}\quad (6)$$

Once all of the plates have been reduced to one system, for every detected object a linear fit is applied to the corresponding transformed multi-epoch observations to obtain the absolute proper motions (and a reference position) as follows:

$$\begin{cases} x_t = x_0 + \mu_x(t - t_0) \\ y_t = y_0 + \mu_y(t - t_0) \end{cases}, \quad (7)$$

where x_t, y_t are the transformed plate (measured) coordinates at epoch t , and μ_x, μ_y, x_0, y_0 are the estimated absolute proper motions and positions in the same coordinate system at the chosen reference epoch $t_0 = \text{J2000.0}$ (see the paragraph on Step 7 in Section 3.3). The x_0, y_0 are the positions at the reference epoch from all plates in different colors and epochs; this decreases the influence of individual random errors and improves the final precision.

3.1.1. Neglecting Parallax

The complete version of Equation (1) usually includes the parallax term, $\pi \Delta P_x$, where π is the parallax and ΔP_x is the difference of the parallax factor at the two epochs of measurement. Therefore, it is important that we speak to the reasons for not including such a term in the reduction model and provide estimates of any possible proper motion bias this decision might cause.

There are three main reasons why we did not include a parallax term in our reductions: (i) the relatively low, plate-scale related, precision of the individual plate measurements (σ_x), (ii) the very coarse time sampling they realize, and (iii) repeated observations of the same fields occur around the same time of the year. Properties (ii) and (iii) are well illustrated in Figures (2) and (3): the upper panel in Figure 2 shows that most of the APOP entries have only three measurements with less than 10% receiving 10 or more; Figure 3, providing the distribution of the folded observing times (folded to the fraction of the year on each observation was taken), clearly reveals a very uneven sampling, unsuitable for properly tracing the parallax ellipse. Actually, the lack of data points in a large interval, ~ 0.35 years, around 0.5 years suggests that parallax induced positional changes are naturally minimized in our data as parallax factor differences tend to be small.

From Section 2, the precision of our best measurements is $\sigma_x \sim 0.15$ arcsec; therefore, dividing this value by the square root of the number of measurements, Nobs, yields a rough estimate of sensitivity to actual parallax shifts. By setting, Nobs = 10, although this actually happens for a very small fraction of the cases (Figure 2), we estimate ($\sigma_\pi \sim \sigma_x / \sqrt{\text{Nobs}} \sim 0.050$ arcsec), i.e., in the best case scenario, parallax would have a chance to show in our data (i.e., as nonlinear effects) but only for distances up to ~ 20 pc. If we now consider again properties (ii), and especially (iii), from above, it becomes clear that parallax direct estimability

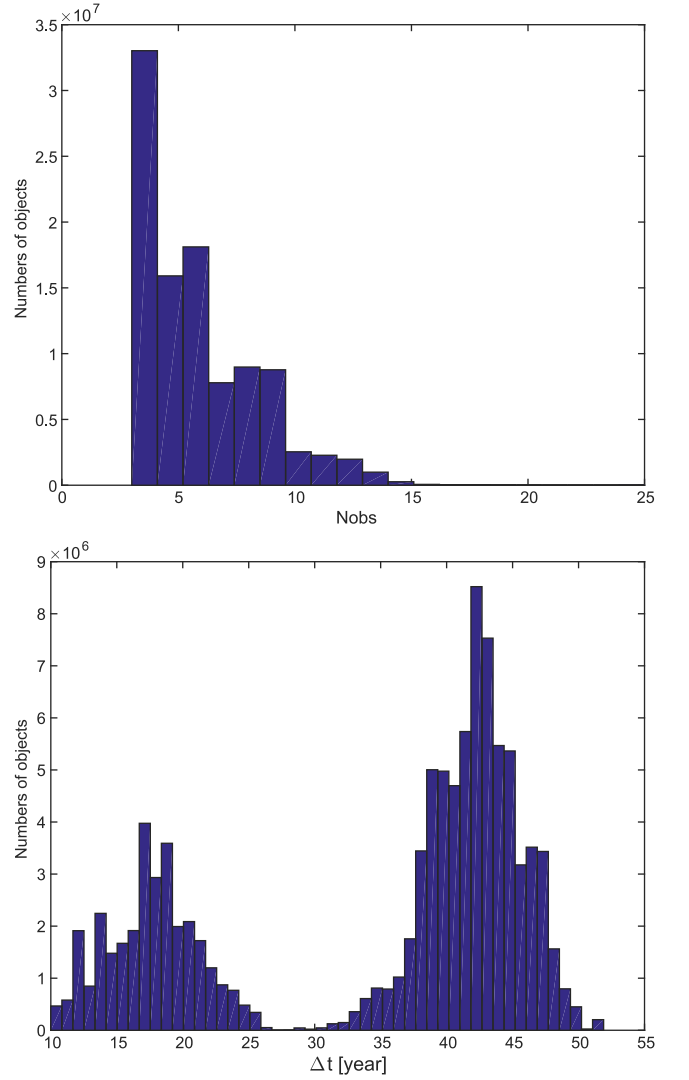


Figure 2. Distribution of the number of measurements per proper motion entry (top); distribution of epoch differences for the proper motions in APOP (bottom).

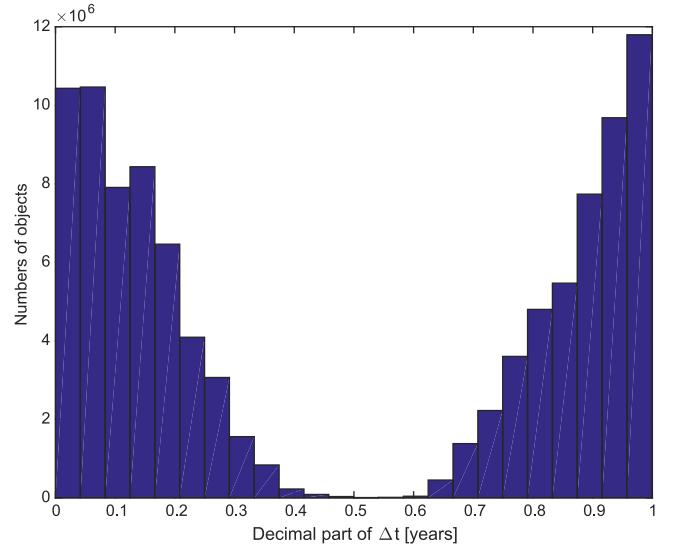


Figure 3. Number of APOP entries against yearly phase.

with our data is unlikely. Under these circumstances forcing a parallactic term in Equation (1) is likely to correlate parallax with proper motion itself, therefore justifying our decision to drop the parallax factors from the adopted reduction model. Yet we still need to address here the possible effects on the APOP proper motions of the parallax term we left unaccounted.

To this end, as recalled in Section 2, pairing plate measurements together (object matching) was done via the GSC2.3 object IDs (no actual re-matching of plate entries); therefore, APOP inherited the same 4 arcsec max matching radius utilized for the construction of the GSC2.3 (Lasker et al. 2008). We anticipate here the characteristics of the proper motions we decided to export to the APOP catalog: each proper motion entry was generated after (1) fitting at least three plate measurements, and (2) rejecting fits with total epoch separation of less than 10 years (see lower panel of Figure 2).

At 20 pc a full parallax shift would show in our results, because of the 10-year condition (No.2) above, as a proper motion bias of ~ 0.005 arcsec yr $^{-1}$. At this distance even disk population stars exhibit proper motions of the order of 0.1 arcsec yr $^{-1}$, for a bias-to-proper-motion ratio of only 5%. With local thick disk and halo stars moving at much higher spatial velocities (up to 10–20 times larger), this bias-to-proper-motion ratio drops to below 1% and 0.3%, for thick disk and halo stars, respectively. As both parallax and proper motion decrease with distance, this ratio could be seen as a value characterizing the quality of the APOP proper motions of the different Galactic populations independent of distance.

In conclusion, the considerations above provide evidence that the proper motion reduction model presented in the previous section is quite robust against parallax effects.

Finally, we still need to address here the effect of the 4 arcsec matching radius recalled before. Actually, for high proper motion samples (roughly higher than 0.4 arcsec yr $^{-1}$ if below -30° decl., and 0.1 arcsec yr $^{-1}$ if above; see the lower panel of Figure 2) involving Galaxy populations like WD and RD stars, this spatial filter can cause the loss of those measurements with the largest epoch differences and therefore may not be the most useful for the best proper motion accuracy. Potential users in need of studying the properties of these important, but relatively small, high proper motion samples will have to decide if the APOP provided values are adequate for their applications.

3.2. Accurate Orientation to the Equatorial System

The overall procedure just discussed only removes the systematic errors between reference and program plates; it can not remove the systematics inherent to the differences between plate-based coordinates and the standard coordinates.

This last registration is obtained using an external reference catalog and an account of the procedure follows.

We use a gnomonic projection to transform the estimated measured coordinates to an equatorial system. Since the Schmidt design provides an equidistant projection, we correct the measured coordinates following Dick (1991):

$$\begin{cases} x_G = x_0 + \frac{1}{3}x_0(x_0^2 + y_0^2) \\ y_G = y_0 + \frac{1}{3}y_0(x_0^2 + y_0^2) \end{cases}, \quad (8)$$

where x_G, y_G are the measured coordinates in a gnomonic projection. By differentiating Equation (8) as a function of time

we find the corresponding relations for proper motions:

$$\begin{cases} \mu_{x_G} = \mu_x \left(1 + x_0^2 + \frac{1}{3}y_0^2 \right) + \frac{2}{3}x_0y_0\mu_y \\ \mu_{y_G} = \mu_y \left(1 + y_0^2 + \frac{1}{3}x_0^2 \right) + \frac{2}{3}x_0y_0\mu_x \end{cases}, \quad (9)$$

where μ_{x_G}, μ_{y_G} are the proper motions in a gnomonic projection.

The transformation between the measured coordinates x_G, y_G and their celestial standard coordinate ξ, η can be expressed as

$$\begin{cases} \xi = ax_G + by_G + c + \varepsilon(x_G, y_G) \\ \eta = a'x_G + b'y_G + c' + \varepsilon'(x_G, y_G) \end{cases}, \quad (10)$$

where a, b, c, a', b', c' are the coefficients of the linear terms of the plate model, i.e., axis direction, scale and origin difference between the measured and standard coordinate systems; $\varepsilon(x_G, y_G)$ and $\varepsilon'(x_G, y_G)$ represent the higher order terms.

If we differentiate Equation (10) with respect to time, we get the proper motions in the standard coordinate system.

$$\begin{cases} \mu_\xi = a\mu_{x_G} + b\mu_{y_G} \\ \mu_\eta = a'\mu_{x_G} + b'\mu_{y_G} \end{cases}, \quad (11)$$

where we have neglected higher order terms, which we estimate to be less than 0.03% of the μ_x, μ_y .

For the objects on the plate, there is a precise geometrical relationship between the standard coordinates and equatorial coordinates i.e.,

$$\begin{cases} \tan(\alpha - \alpha_0) = \frac{\xi}{\cos \delta_0 - \eta \sin \delta_0} \\ \tan(\delta) = \frac{\eta \cos \delta_0 + \sin \delta_0}{\cos \delta_0 - \eta \sin \delta_0} \cos(\alpha - \alpha_0) \end{cases}, \quad (12)$$

where α_0, δ_0 are the equatorial coordinates of the tangent point.

Finally, the rigorous relationship between proper motions in the equatorial and standard systems is obtained by differentiating Equation (12) as a function of time, i.e.,

$$\begin{cases} \mu_\alpha = \cos^2(\alpha - \alpha_0) \\ \left(\begin{aligned} & \frac{1}{\cos \delta_0 - \eta \sin \delta_0} \mu_\xi \\ & + \frac{\xi \sin \delta_0}{(\cos \delta_0 - \eta \sin \delta_0)^2} \mu_\eta \end{aligned} \right) \\ \mu_\delta = \cos^2(\delta) \\ \left(\begin{aligned} & \frac{\cos(\alpha - \alpha_0) \cos \delta_0}{\cos \delta_0 - \eta \sin \delta_0} \mu_\eta \\ & + \frac{\cos(\alpha - \alpha_0) (\eta \cos \delta_0 + \sin \delta_0) \sin \delta_0}{(\cos \delta_0 - \eta \sin \delta_0)^2} \mu_\eta \\ & - \frac{(\eta \cos \delta_0 + \sin \delta_0) \sin(\alpha - \alpha_0)}{\cos \delta_0 - \eta \sin \delta_0} \mu_\alpha \end{aligned} \right) \end{cases}. \quad (13)$$

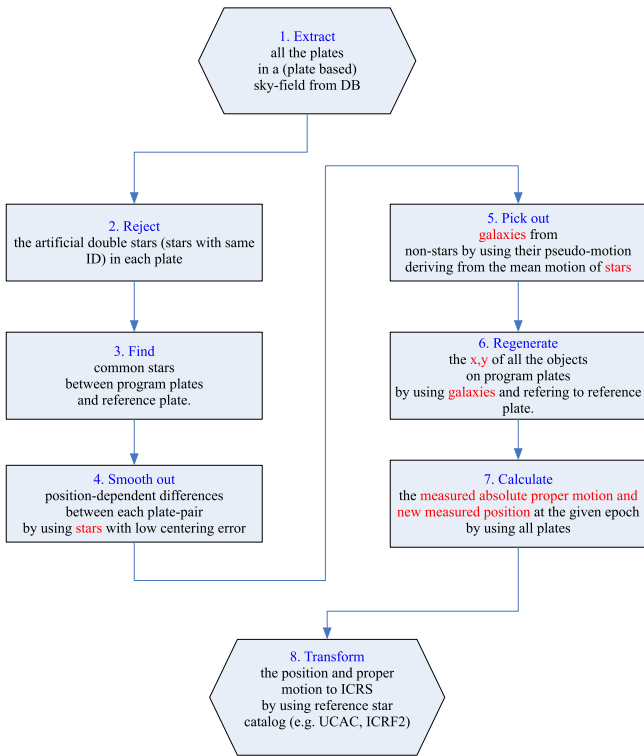


Figure 4. Flowchart of the processing pipeline.

3.3. Processing Pipeline

We developed a FORTRAN pipeline based on the above principles to determine absolute proper motions from the COMPASS database. The flowchart (Figure 4) summarizes the specific steps and techniques used to remove the systematic errors and to acquire the absolute proper motions. Key steps in the flow chart are detailed below.

In Steps 1–3 we extract all matches on the plates overlapping with the reference plate. Only objects that appear in all plates are used to calibrate the fit to the reference plate system.

In Step 4, a moving-mean-like method is applied to remove the mean shift (PdE and the mean proper motions of reference stars) in x and y between the program and reference plate. Only stellar objects are used in the calculation of the moving mean but the result is applied to all detections. In order to attain the most accurate coordinate transformation, we select reference stars with good image quality (i.e., with low centering errors, see Section 3.1). In particular, we use detections classified as star in the range $(m_{\text{lim}} - 4.5) \leq m \leq (m_{\text{lim}} - 2.0)$, where m_{lim} is the limiting magnitude of the plate, ~ 20.5 in R_f . In general we find around 500 stars degree $^{-2}$ well distributed on the plate. There are several methods for removing the PdE, such as a global plate solution using high-order polynomials, the astrometric MASK (Taff et al. 1990; Lattanzi & Bucciarelli 1991), the Infinitely Overlapping Circles (IOC, Taff et al. 1992), the sub-plate method (Taff 1989) etc. All these methods have pros and cons: the Schmidt plate distortions would require very complicated global solutions, the MASK method is very sensitive to the number of reference objects and the grid size, the IOC has problems at the plate boundaries and the sub-plate method can lead to non-uniformities.

We developed a variant of the sub-plate method, the moving sub-plate method, that is sensitive to local signals while

ensuring an increased level of uniformity. The moving sub-plate method starts by transforming the measured coordinates x_2, y_2 on the program plates to the corresponding coordinates x_1, y_1 on the reference plate using cubic polynomials (Equation (14)). This will remove most of the large-scale errors (e.g., spherical deformation).

$$\begin{cases} x_1 = f(x_2, y_2) \\ y_1 = g(x_2, y_2) \end{cases}, \quad (14)$$

where the functions f and g are complete cubic polynomials.

The residuals $\Delta x, \Delta y$, from the global (whole plate) cubic polynomial fit are then used in the following linear relations:

$$\begin{cases} \Delta x = ax_2 + by_2 + c \\ \Delta y = a'x_2 + b'y_2 + c' \end{cases}, \quad (15)$$

where a, b, c, a', b', c' allow for zero point, rotation, and scale difference at a local level.

To fit Equation (15) we select nearby reference stars within a radius of 20 arcmin from the program object. If more than 15 stars were found, they were ranked with distance from the program star and the first 15 were used for the fit; with less than 3 reference stars no correction was computed. Therefore depending on actual star density, the effective radius of a moving sub-plate can be much smaller than 20 arcmin. Applying this correction to all program objects removes most of the small scale errors (See Figure 5). After Step 4, the mean displacement due to proper motion of the reference objects is locally zero, while that of galaxies is not.

In Step 5 we use Equation (16) on all the non-stars to fit a linear (coordinate only) model to estimate the mean proper motion components for any given plate pair, i.e., the $-\bar{\mu}_x \Delta t$ in Equation (5), and its analog for the y direction.

$$\begin{cases} \Delta x = x_1 - x_2 = ax_2 + by_2 + c \\ \Delta y = y_1 - y_2 = a'x_2 + b'y_2 + c' \end{cases}, \quad (16)$$

where x_2, y_2 are intended as the measured coordinates of non-stars on the program plate corrected for the systematics calculated in Step 4. As per Equation (5), we iterate rejecting any objects with residuals greater than 2.6 standard deviations⁹ per coordinate.

The objects that survive this selection are likely to be, or act like (i.e., non-stellar objects with zero proper motions), genuine galaxies. Figure 6 shows the final mean (pseudo) proper motion of the galaxies after completing Step 5 for the same plate pair as that of Figure 5.

In Step 6 once the galaxies positions are corrected using the fitted coefficients of Equation (16), a two-dimensional map of the galaxies residuals shows that some PdE are still present. These are smoothed out using again the moving sub-plate method but this time using the selected galaxies as reference objects. The residual corrections found at this stage are applied to all of the objects. The subset of these values relative to the galaxies is then spatially binned and plotted against magnitude and color to seek for any remaining Mde and/or Cde signals.

⁹ We found that the 2.6σ value (i.e., 99.0% probability of being within the acceptable standard deviation) was optimal: a larger value provided many more objects to use with Equation (16) but larger fit errors (because of the inclusion of larger fraction of spurious galaxies, usually unresolved binaries or defects); on the other hand, a smaller threshold meant losing too many good candidates for the fit.

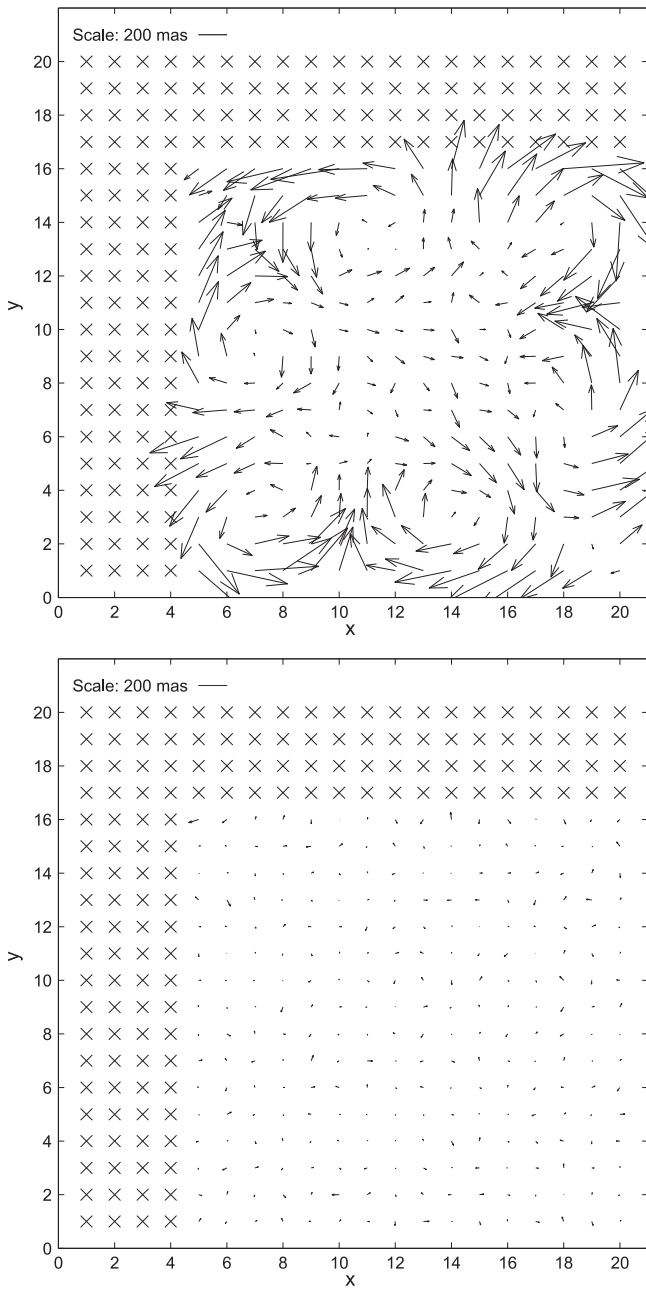


Figure 5. Upper figure shows the PdE as a function of plate position after the cubic polynomials fitting. The vector represents the magnitude and direction of the average residual for the reference stars in that region of the plate. The data shown here come from the plate XP715 (epoch = 1996.3, $l = 266^{\circ}9$, $b = 69^{\circ}2$) and XE494 (epoch = 1955.3). The lower figure shows the same data as the one above after applying the moving sub-plate method. No observable PdE remains after this step. The marker “x” symbols indicate there are no common stars in those plate regions.

In case, these are treated by simple one-dimensional linear interpolation in between the magnitude or color bins. This procedure removes most of the MdE and CdE between program and reference plates.

At this step we apply the mean motion to the stellar objects and remove it from the galaxies. From Figures 7 to 8 we note that both MdE and CdE were significantly reduced.

In Step 7 for all of the plate objects we fit Equation (7) to determine absolute proper motions and positions at the given epoch J2000.0. We then correct the measured coordinates and

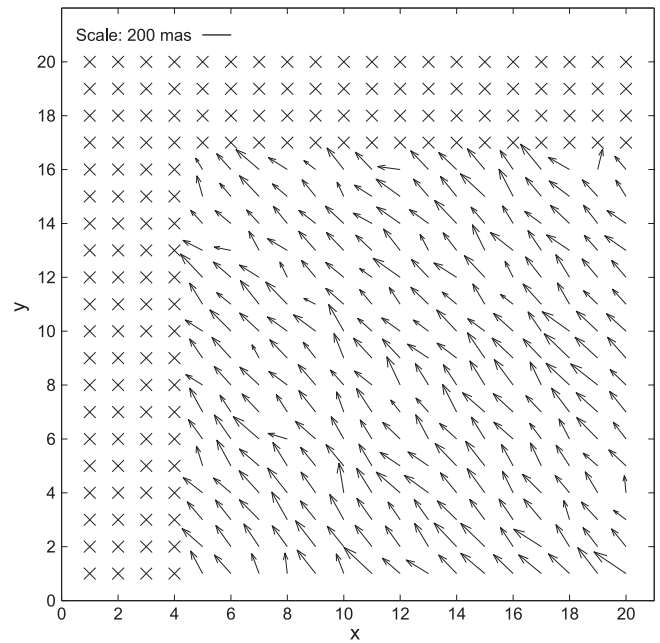


Figure 6. Mean pseudo “proper motion” of galaxies as a function of plate position.

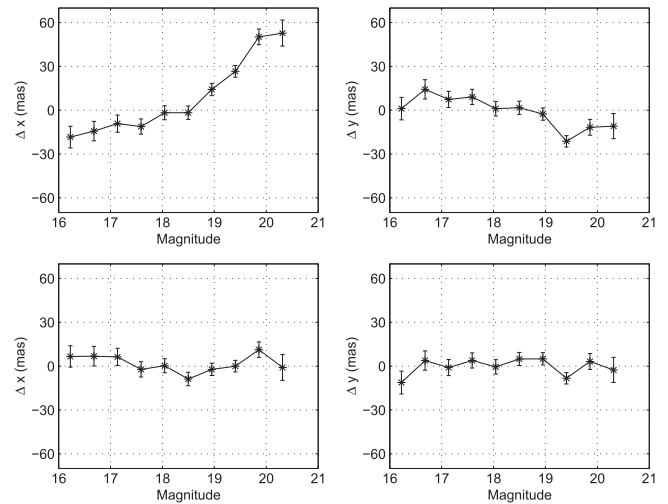


Figure 7. Mean residuals of the pseudo “proper motion” of the galaxies as a function of magnitude after Step 6. The upper two figures are the results without a magnitude term, while the lower panels are results with that term included. The magnitude is binned in 0.46 mag bins, with 300–2000 objects per bin for the different magnitudes.

absolute proper motions derived in an equidistant projection to a gnomonic projection by using Equations (8) and (9).

In Step 8 we use the Fourth US Naval Observatory CCD Astrograph Catalog (UCAC4, Zacharias et al. 2013) and Equations (10)–(13) to transfer absolute proper motions and positions to the celestial reference frame. Moreover, we corrected the frame bias between APOP and the International Celestial Reference System (ICRS) by using 1288 objects (most of them are faint Quasi-stellar objects; QSOs) common to the radio ICRF2 catalog (Ma et al. 2009). To establish the

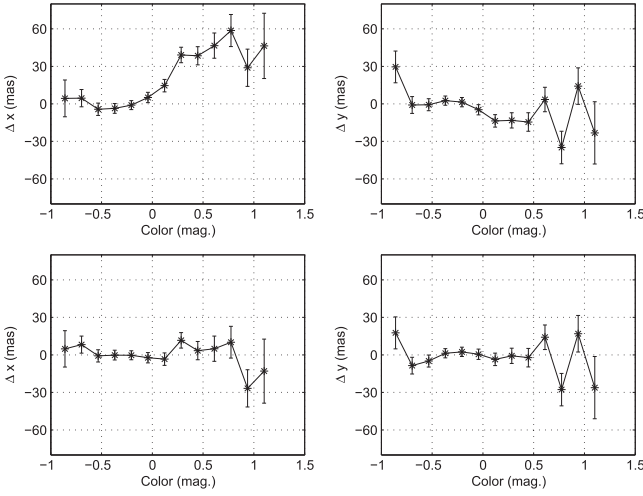


Figure 8. Same residuals as Figure 7, but as a function of color. The upper two figures are the results without a color term, while the lower panels are results with that term included. The color, $B_J - R_F$, is binned in 0.16 mag bins, with 60–2000 objects per bin as a function of color. The plots clearly show that the systematic corrections become statistically ineffective for colors larger than ~ 0.5 in Δy due to small number of objects.

orientation to the standard frame, we use the following formula

$$\begin{aligned} \mathbf{r}_{\text{ICRF2}} &= R_Y(\xi_y) R_X(\xi_x) R_Z(\xi_z) \cdot \mathbf{r}_{\text{APOP}} \\ &= \begin{pmatrix} 1 & \xi_z & -\xi_y \\ -\xi_z & 1 & \xi_x \\ \xi_y & -\xi_x & 1 \end{pmatrix} \cdot \mathbf{r}_{\text{APOP}} \end{aligned} \quad (17)$$

where $\mathbf{r}_{\text{ICRF2}}$ and \mathbf{r}_{APOP} are the direction vectors to the common objects in both ICRF2 and APOP, respectively; ξ_x , ξ_y , ξ_z are the three small rotation angles needed to register the APOP coordinate frame about the x , y and z axes of the ICRF2. A least-squares fit to Equation (17) provides estimates of those three angles: $\xi_z = 27.73 \pm 0.12$ mas, $\xi_x = -7.30 \pm 0.15$ mas, and $\xi_y = 2.21 \pm 0.06$ mas; these are used to bring APOP onto ICRF2. The ξ_x and ξ_y values are similar to those found in Zacharias & Zacharias (2014), while the ξ_z rotation difference is considerably large ($\xi_z = 7.61 \pm 1.21$ in Zacharias' work). The actual cause is not clear at the moment but it could reside in the different samples used for the registration. After performing the transformation, the coordinate axes realized by our astrometric data are believed to be aligned, at least formally, with the extragalactic radio frame to within ± 0.2 mas at the reference epoch J2000.0.

4. CATALOG ACCURACY AND PRECISION

We can estimate the accuracy and precision of our proper motions to provide us with a final external check. We expect the accuracy defined by the absolute zero point from Equation (16), assuming the observational errors are equally distributed among the fitted parameters, to be approximately given by

$$\sigma_{\text{zero}} = \frac{\sqrt{6} \sigma_g}{|\Delta t| \sqrt{N_g}}, \quad (18)$$

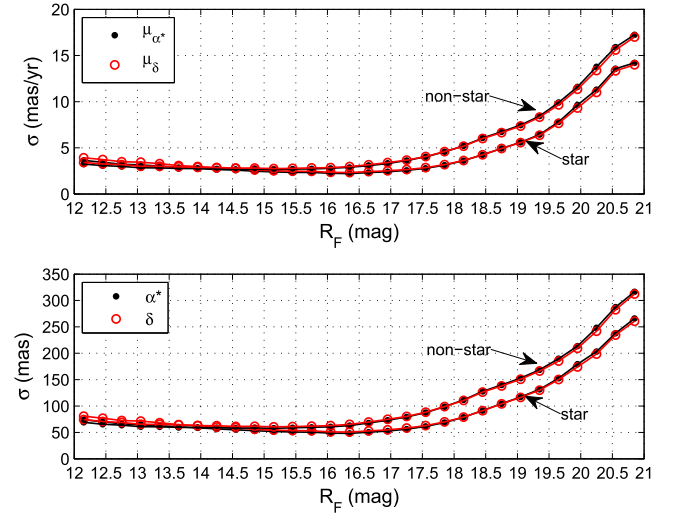


Figure 9. Mean formal errors of APOP absolute proper motions (μ_{α^*} , μ_δ) and positions (α , δ) of stars and non-stars as a function of R_F magnitude. The magnitude is binned in 0.3 mag bins, with at least 100,000 objects per bin. The marker * in the μ_α indicates multiplication by $\cos(\delta)$. Top: the formal errors of absolute proper motions in mas yr^{-1} ; bottom: the formal errors of positions in mas.

where σ_g is the positional measuring error of galaxies, 6 is the number of unknown parameters and Δt is the epoch difference between two plates. This empirical error estimate has been confirmed by examining the formal error using simulated data. The range of positional measuring error of galaxies is in the range $0''.2 < \sigma_g < 0''.5$ for objects brighter than $R_F = 20.0$, the time baseline range is $12 < |\Delta t| < 45$ years and the number of galaxies is $8000 < N_g < 20000$. This corresponds to a zero-point (absolutization) error of $0.1 < \sigma_{\text{zero}} < 1.1 \text{ mas yr}^{-1}$.

If we assume the observations are evenly distributed about the mid-epoch we find that the formal error of each proper motion component from Equation (7) is

$$\sigma_\mu = \frac{\sigma_s}{\langle |\Delta t| \rangle \sqrt{N_{\text{obs}}}}, \quad (19)$$

where σ_s is the positional error, N_{obs} is the number of observations of a star and $\langle |\Delta t| \rangle$ is the average time difference between the various observations and the mid-epoch. The range of positional measuring error is $\sim 0''.2 < \sigma_g < 0''.3$ for stars brighter than $R_F = 20.0$, the number of observations $3 < N_{\text{obs}} < 15$, and the average time differences $12 < |\Delta t| < 45$ years. This corresponds to a range of overall error of $1 < \sigma_\mu < 14 \text{ mas yr}^{-1}$.

We reduced all the plates with $|b| \geq 27^\circ$ and carried out an error analysis to certify the reliability of the calibration software and the quality of the final catalog, as described in the next sections.

4.1. Internal Precision

For each object, we calculated positions and proper motions by fitting Equation (7) utilizing all of the measurements from the different epochs and colors. This provides the formal errors of the calibrated parameters ($\mu_{\alpha^*} = \mu_\alpha \times \cos(\delta)$, μ_δ , α , δ), and an internal check of the APOP quality.

In Figure 9 we plot the mean formal errors and find them to be consistent in both R.A. and decl. even though the two

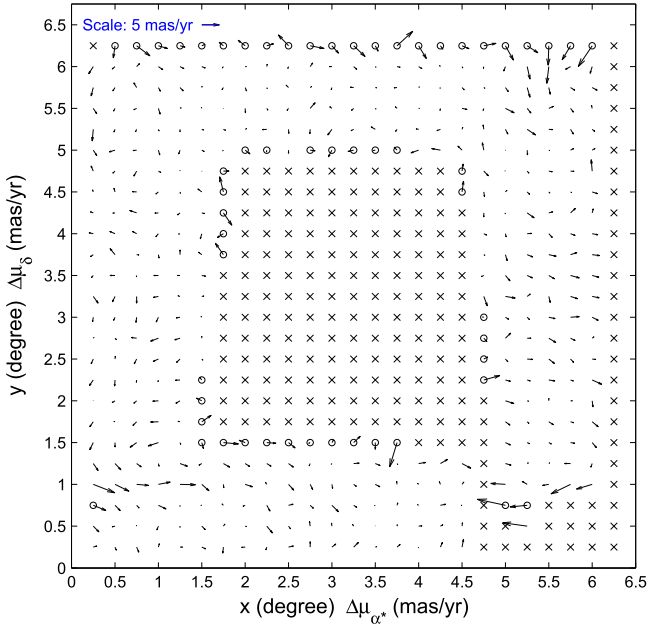


Figure 10. Differences of proper motions ($\Delta\mu_{\alpha^*}$, $\Delta\mu_{\delta}$) of common objects in the reference plate XP216 and overlapping plates as a function of position. The “/” indicates the magnitude and direction of the differences of the average proper motions. A 5 mas yr⁻¹ scale arrow is plotted at the top left corner. The size of each bin is 0.25×0.25 degree² and they contain on average 300 objects per bin. The marker “x” indicates no objects in common, while a “o” indicates that the number of the common objects is less than 100.

coordinates were treated independently. For stellar objects, the internal accuracy of the proper motions is better than ± 4 mas yr⁻¹ for objects brighter than $R_F = 18.5$, increasing to 9 mas yr⁻¹ at $R_F = 20.0$ and to 14 mas yr⁻¹ for objects with $20.0 < R_F < 20.8$. The internal accuracy of the stellar positions is better than ± 100 mas for objects brighter than $R_F = 18.5$, increasing to 260 mas for objects with magnitude $R_F \sim 20.8$. The offset between the star and non-star objects is consistent with the ~ 1.5 times larger measurement errors of non-stellar objects.

We note that objects close to the magnitude limit (i.e., $20 < R_F < 21$) have larger errors than predicted; APOP parameters and errors should be used with caution for objects fainter than $R_F = 20$.

An internal check of the accuracy of APOP proper motions is provided by multiple estimates for the same stellar objects appearing in overlap regions between adjacent reference plates. In Figure 10 we display the mean offset between the proper motions calibrated on two adjacent reference plates. The differences are plotted based on the position in the central reference XP216 ($l = 151^\circ.4$, $b = 62^\circ.8$), which has a typical 1.5×6.5 overlap with four adjacent plates XP215 (left), XP217 (right), XP170 (top) and XP266 (bottom). There are no large scale offsets in the overlap regions, but some shifts of ~ 1.8 mas yr⁻¹ appear at small scales, particularly at the bottom left of the central plate. These are very likely caused by the uncertainty in the correction of the absolute zero point by the galaxies.

4.2. External Accuracy

QSOs have star-like images and since they are extragalactic, they do not exhibit any time-dependent displacement. Thus, we can use the mean and dispersion of their measured motions to

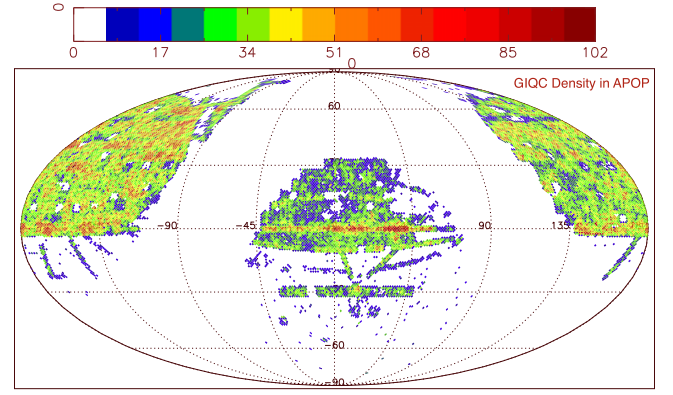


Figure 11. Density distribution of 376,490 QSOs found in the APOP catalog via cross-matching with the GIQC catalog.

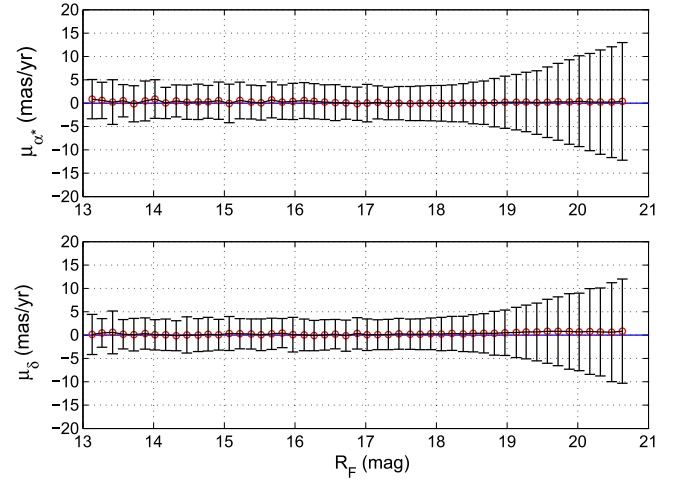


Figure 12. Distribution of absolute proper motions (μ_{α^*} , μ_{δ}) of QSOs as a function of magnitude. The red circles indicate the mean of μ_{α^*} and μ_{δ} in that magnitude bin and the error bar shows their standard deviation, which, following the assumption that QSO should have zero proper motions, are indicative of the proper motion random errors. The figure clearly shows a ~ 0.6 mas yr⁻¹ systematic offset in decl. proper motions for QSOs fainter than 18 mag.

evaluate the zero point and overall precision of stellar proper motions. Here we use QSOs as an independent and direct determination of the APOP catalog quality.

The Gaia Initial QSO Catalog (GIQC; Andrei et al. 2009) is chosen as the source list for known QSOs. The objects are broadly distributed within the SDSS region, though their density is not uniform (see Figure 11). Figures 12–14 show the mean proper motions of the GIQC QSOs and indicate that there is a very good agreement between the external and theoretical error estimates of proper motions for the magnitude range $R_F < 20.5$. In particular, from this sample of QSOs we find a proper motion zero point error of 0.6 mas yr⁻¹. As a verification of the internal estimates, Figure 15 shows the formal errors of positions (α , δ) of QSOs as a function of magnitude, and indicate that they are consistent with stellar objects.

In addition to the GIQC, we also compared APOP with other external catalogs. The most natural comparison would be with the Positions and Proper Motion XL catalog (hereafter PPMXL, Roeser et al. 2010) the largest most recent catalog with absolute proper motions. This was constructed by combining USNO-B1.0 and the Two Micron All Sky Survey (Skrutskie

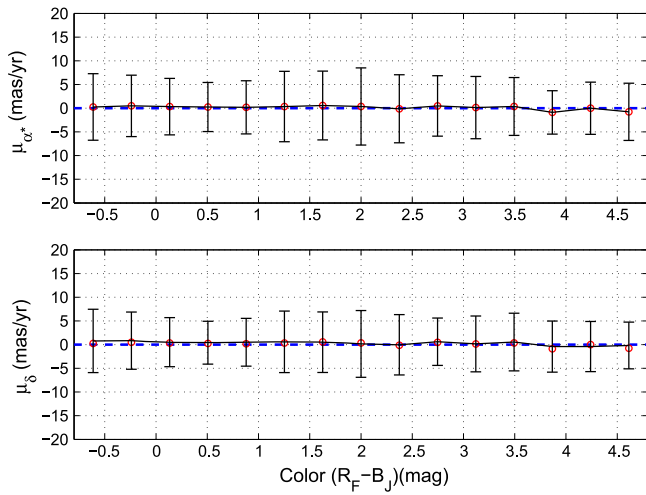


Figure 13. The absolute proper motions found for the QSOs as a function of color.

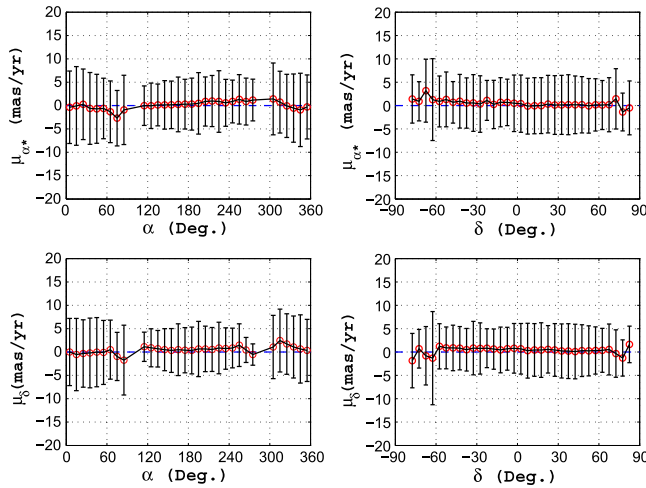


Figure 14. Absolute proper motions found for the QSOs as a function of α and δ . As evidenced here, absolute proper motions data around the Large Magellanic Cloud region (center at $\alpha_o = 80^\circ.9$, $\delta_o = -69^\circ.7$, apparent dimension is $10^\circ.8 \times 9^\circ.2$) are not reliable and could cause an offset in μ_s .

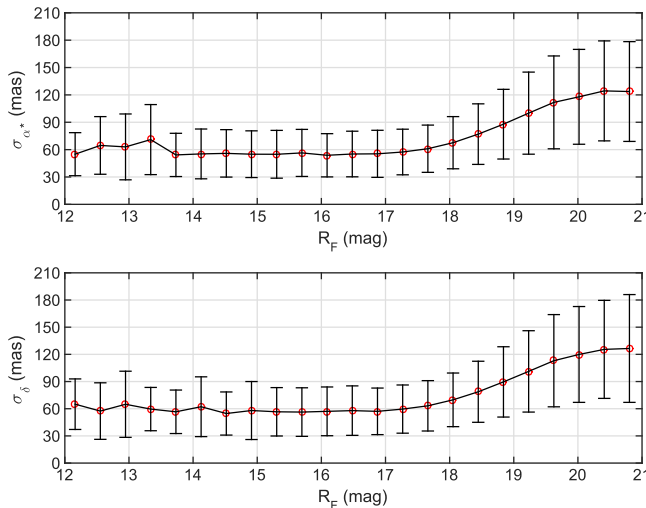


Figure 15. Formal errors of the QSO positions as a function of magnitude. The red circles indicate the mean formal errors of α^* and δ in that magnitude bin and the error bar shows their standard deviation. The magnitude is binned in 0.4 mag bins, with 38–21,539 objects per bin as a function magnitude.

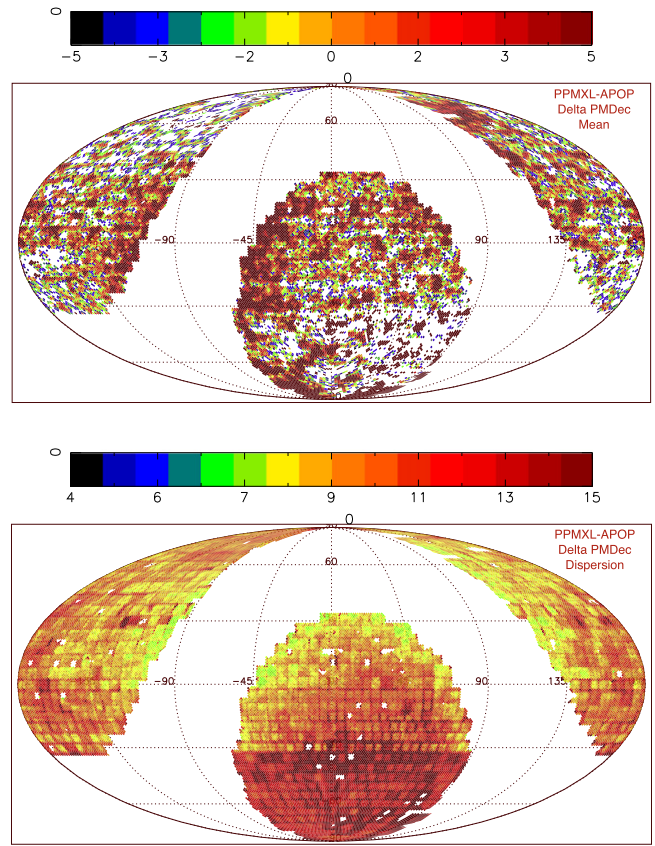


Figure 16. Mean (top figure) and dispersion (bottom figure) of differences in μ_s between APOP and PPMXL as a function of sky location in an equatorial coordinate system. The differences in μ_{α^*} are quite similar. These plots are based on the 82,722,482 common objects between these two catalogs divided in HEALPix (Hierarchical, Equal Area, and iso-latitude Pixelisation) level six regions.

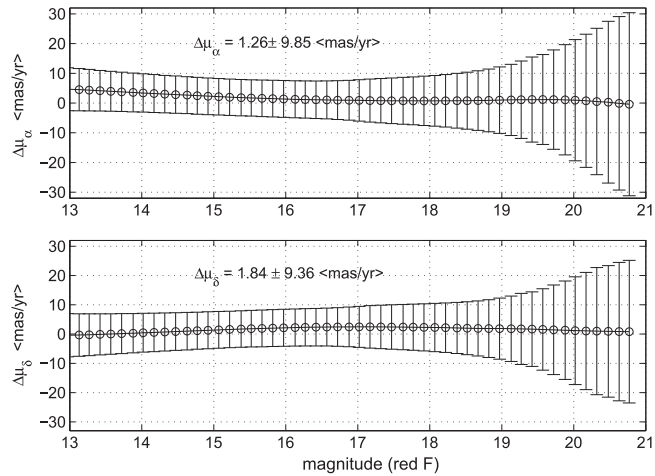


Figure 17. Mean and dispersion (rms) of the proper motion differences between APOP and PPMXL as a function of magnitude.

et al. 2006) catalogs. Figures 16 and 17 illustrate that there is a systematic offset between these two catalogs in absolute proper motions.

We also selected a subset of the GIQC QSOs that were in both the APOP and the PPMXL for a comparison. Figure 18 shows that the offset between the two catalogs is mostly due to a zero point problem in the PPMXL. Also, for most of the

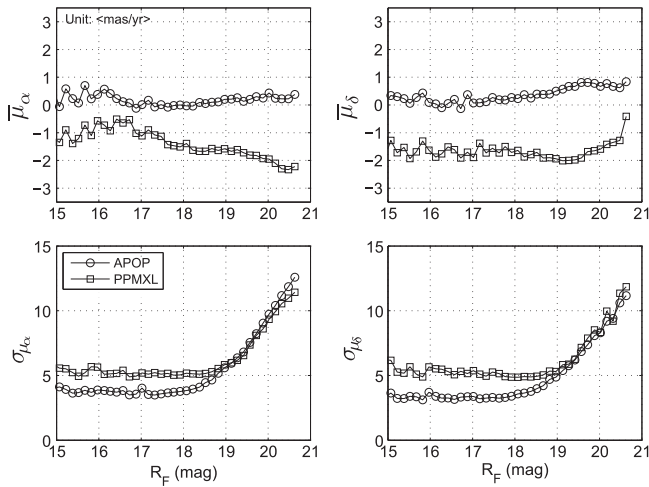


Figure 18. Mean and dispersion of the absolute proper motions of the 360,127 QSOs common to both the APOP and the PPMXL as a function of magnitude.

magnitude range the APOP has smaller proper motion dispersion.

4.3. Galactic Clusters in APOP

Since the field of view of the Schmidt plate is very large (6.5×6.5 sq. deg) the mean proper motion of stellar objects could vary across the plate. For example, clusters generally cover a significant part of a photographic plate. Using the stars in Step 4 to remove the PdE we risk also “removing” the proper motions for this group of objects. Theoretically, we believe our procedure returns the mean proper motions to those groups with Steps 5 and 6. The proper motions of the Praesepe cluster in Figure 19 indicate that at least for this cluster the procedure has worked.

4.4. The Final Catalog

The catalog is available at Strasbourg’s astronomical Data Center (<http://cds.u-strasbg.fr>, catalog I/331); the description of the catalog data is detailed in Table 1. In particular, APOP derived positions and proper motions are at epoch J2000.0 and on the ICRS-defined equator.

Given the evidence provided, we believe that APOP’s proper motions are reliable for operational applications as well as astrophysical research. However, the potential users should remember the following.

1. The accuracy is best for objects with $\delta \geq -30^\circ$ because of the 45-year epoch difference between first and second generation survey plates; at lower declinations the quality can be about four times worse than that due to a time base of only 12 years.
2. Our data around the Large Magellanic Cloud region (center at $\alpha_o = 80:9$, $\delta_o = -69:7$ and $10:8 \times 9:2$ in size) are not entirely reliable, as the region is too crowded, which caused object detection to generate many spurious objects.
3. The accuracy may not be sufficiently good for objects with magnitude $R_F < 15.0$ due to a lack of bright galaxies on some plates and decreasing measuring precision due to heavier saturation effects. At this bright end, users should at least compare APOP’s values to those listed in bright

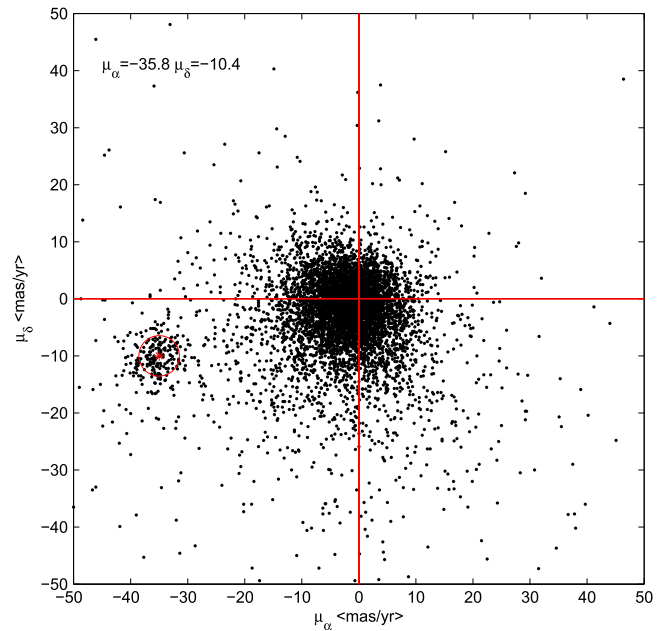


Figure 19. Proper motion vector-point diagram for all the objects in APOP with magnitude $R_F < 18.0$ in the area of the *Praesepe* cluster. A tight group at $\mu_{\alpha*} = -35.8 \text{ mas yr}^{-1}$, $\mu_{\delta} = -10.4 \text{ mas yr}^{-1}$ indicates the location of *Praesepe* and permits a segregation between the cluster and field stars. In addition, this value is quite close to the *Hipparcos* data for *Praesepe*, which is $\mu_{\alpha*} = -35.81 \text{ mas yr}^{-1}$, $\mu_{\delta} = -12.85 \text{ mas yr}^{-1}$ (van Leeuwen 2009).

absolute catalogs like, e.g., UCAC4 (Zacharias et al. 2013).

4. As explained in Section 3.1.1, when used in accurate work, especially with high proper motion stars, APOP values should be taken with caution because of possible residual parallax effects.

The items above provide users with the proper information to decide if the APOP entries are adequate for their applications.

5. CONCLUSIONS AND FUTURE WORK

The main results from our study are the following.

1. The principles and techniques suitable for the derivation of absolute proper motions from survey plates, including the treatment for position, magnitude and color systematics are described.
2. The realization of the APOP catalog is presented. Because of the direct use of extragalactic objects, the catalog sky coverage is limited to the regions outside the galactic plane ($|b| \geq 27^\circ$).
The internal and external accuracies of this new catalog are consistent with expectations. The overall accuracy of the absolute proper motions is in the $3\text{--}9 \text{ mas yr}^{-1}$ range, with an absolute zero point error estimated at better than 0.6 mas yr^{-1} ; this proves the feasibility and reliability of the principles and methods adopted for its construction. The average position accuracy is about 150 mas (per coordinate), with a systematic deviation from the ICRS around 0.2 mas.
3. A new method to refine source classification and select bona fide galaxies by implementing the concept of induced pseudo-motion is presented.

Table 1
Description of the APOP Data Table

Number	Type	Units	Label	Explanations
1	Char	null	ID	source identifier ^a
2	Int	null	Type	Classification ^b
3	Double	degree	RA	α_{ICRS} , J2000.0
4	Double	degree	DE	δ_{ICRS} , J2000.0
5	Float	mas	sigRA	Error in α
6	Float	mas	sigDE	Error in δ
7	Float	mas/year	PR	$\mu_{\alpha}\cos(\delta)$
8	Float	mas/year	PD	μ_{δ}
9	Float	mas/year	sigPR	Error in $\mu_{\alpha}\cos(\delta)$
10	Float	mas/year	sigPD	Error in μ_{δ}
11	Int	null	Nobs	Number of observations ^c
12	Float	year	Dt	Maximal time differences ^d
13	Float	mag	Rmag	R_r photographic magnitude ^e
14	Float	mag	Bmag	B_r photographic magnitude
15	Float	mag	Nmag	I_N photographic magnitude
16	Float	mag	Vmag	V photographic magnitude
17	Float	mag	Jmag	2MASS J magnitude ^f
18	Float	mag	Hmag	2MASS H magnitude
19	Float	mag	Kmag	2MASS K_s magnitude

Notes.

^a The ID is the source identifier for an object in the APOP, which is as same as the source identifier of that object in GSC2.3 catalog. ^b The classification is based on the following codes: (0): Star as defined in the GSC2.3. (1): Stars used as reference objects. (2): QSOs from the GIQC catalog. (3): Non-stars as defined in the GSC2.3. (4): Non-stars indicated as extragalactic objects from Section 3.2 Step 5. ^c The Nobs is the number of plates used for deriving the μ_{α} , μ_{δ} of that object. ^d The Dt is the maximal time differences between the plates used for the calculation. ^e The magnitude data are extracted directly from the GSC2.3 catalog. Users can identify the exact meaning by looking at “Table 3” in GSC2.3 paper (Lasker et al. 2008). ^f The photometric data are the near-infrared J (1.25 μm), H (1.65 μm), and K_s (2.16 μm) from the 2MASS catalog (Skrutskie et al. 2006).

We intend to apply a variant of this procedure to the whole GSC-II database to produce the GSC2.4. Some of the methods in this paper are only applicable in regions with significant numbers of extragalactic objects; therefore, we are working on new procedures for the galactic plane. Another residual source for concern is the offset between the magnitude systems of stars and galaxies (Lasker et al. 2008). This reduces the effectiveness of removing the magnitude and color systematic errors by using galaxies.

Further investigations will clarify these issues as we prepare to extend APOP to the all sky with the production of GSC2.4.

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This research has made use of the MCS database server system, developed by Giorgio Calderone and Luciano Nicastro, operated at OATo and SHAO. Finally, we wish to thank the people who gave us their suggestions and assistance throughout the realization of APOP, and especially Ming Zhao, William F. van Altena, Ramachrisna Teixeira, Nadia Maigurova, Alexandre H. Andrei, Ronald Drimmel, Leigh Smith, Zhengyi Shao and Zi Zhu.

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